# High-dimensional CCA 

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## Introduction and outline

Canonical Correlation Analysis (CCA) is much like Principal Component Analysis (PCA).

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Structure of talk

- Population CCA
- CCA as a tool for data analysis
- Our specific motivations and contributions


## Population CCA

In words: Given random variables $X \in \mathbb{R}^{p}, Y \in \mathbb{R}^{q}$ find linear combinations $u^{T} X, v^{T} Y$ with maximal correlation, successively, subject to orthogonality.

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In maths: Inductively define $u_{k}, v_{k}$ by

```
\(\underset{u \in \mathbb{R}^{p}, v \in \mathbb{R}^{q}}{\operatorname{maximize}} \operatorname{Cov}\left(u^{T} X, v^{T} Y\right)\)
subject to \(\operatorname{Var}\left(u^{\top} X\right)=\operatorname{Var}\left(v^{\top} Y\right)=1\),
    \(\operatorname{Cov}\left(u^{T} X, u_{j}^{T} X\right)=\operatorname{Cov}\left(v^{T} Y, v_{j}^{T} Y\right)=0 \quad\) for \(j=1, \ldots, k-1\).
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\operatorname{Cov}\left(u^{\top} X, u_{j}^{\top} X\right)=\operatorname{Cov}\left(v^{\top} Y, v_{j}^{\top} Y\right)=0 \quad \text { for } j=1, \ldots, k-1
$$

## Notation:

- $\rho_{k}$ the optimal value called $k^{\text {th }}$ canonical correlation
- $u_{k}^{T} X, v_{k}^{T} Y$ called canonical variates
- $u_{k}, v_{k}$ called weights


## Visualisation of CCA

$\underset{u \in \mathbb{R}^{\rho}, v \in \mathbb{R}^{G}}{\operatorname{maximize}} \operatorname{Cov}\left(u^{\top} X, v^{\top} Y\right)$
subject to $\operatorname{Var}\left(u^{\top} X\right)=\operatorname{Var}\left(v^{\top} Y\right)=1$,
$\operatorname{Cov}\left(u^{T} X, u_{j}^{T} X\right)=\operatorname{Cov}\left(v^{T} Y, v_{j}^{\top} Y\right)=0 \quad$ for $j=1, \ldots, k-1$.


## Matrix formulation

$$
\begin{aligned}
& \underset{u \in \mathbb{R}^{p}, v \in \mathbb{R}^{q}}{\operatorname{maximize}} \operatorname{Cov}\left(u^{T} X, v^{T} Y\right) \\
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Weights are not the only interesting vectors - let's inspect matrix form - but skim links to rest of matrix analysis for now...

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\begin{aligned}
\underset{u \in \in \mathbb{R}^{P}, v \in \mathbb{R}^{9}}{\operatorname{maximize}} & \operatorname{Cov}\left(u^{\top} X, v^{\top} Y\right) \\
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& \underset{u \in \mathbb{R}^{p}, v \in \mathbb{R}^{q}}{\operatorname{maximize}} u^{T} \Sigma_{x y} v \\
& \text { subject to } u^{T} \Sigma_{x x} u=1, v^{T} \Sigma_{y y} v=1, \\
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Notation: Define canonical loadings

$$
\Sigma_{x x} u_{k}=\operatorname{Cov}\left(X, u_{k}^{T} X\right), \quad \Sigma_{y y} v_{k}=\operatorname{Cov}\left(Y, v_{k}^{T} Y\right)
$$

## Reconstruction

Orthonormality constraints $u_{k}^{T} \sum_{x x} u_{j}=v_{k}^{T} \sum_{y y} v_{j}=\delta_{j k}$ for $1 \leq j \leq k-1$.
So $\left(u_{k}\right),\left(\Sigma_{x x} u_{k}\right)$ and $\left(v_{k}\right),\left(\Sigma_{y y} v_{k}\right)$ are each pairs of dual bases.

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Hence

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X=\sum_{k=1}^{p} \Sigma_{x x} u_{k}\left\langle u_{k}, X\right\rangle, \quad Y=\sum_{k=1}^{q} \Sigma_{y y} v_{k}\left\langle v_{k}, Y\right\rangle
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Probabilistic CCA: Consider the model

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\begin{array}{rlrl}
Z & \sim \mathcal{N}\left(0, I_{d}\right), & \min (p, q) \geq d \geq 1 \\
X \mid Z & \sim \mathcal{N}\left(W_{1} Z+\mu_{1}, \Psi_{1}\right), & W_{1} \in \mathbb{R}^{p \times d}, \Psi_{1} \succcurlyeq 0 \\
Y \mid Z & \sim \mathcal{N}\left(W_{2} Z+\mu_{2}, \Psi_{2}\right), & & W_{2} \in \mathbb{R}^{p \times d}, \Psi_{2} \succcurlyeq 0
\end{array}
$$

Then MLEs for $W_{1}, W_{2}$ are essentially matrices of canonical loadings

## Practical Uses

- High-level: two sets of data and want to understand interactions
- Different perspectives:
- stats: estimation
- bio-informatics: algorithm for data matrices, part of pipeline...
- Uses: Dimension reduction, visualisation / interpretation, multi-view / self-supervised learning
- Motivating Example: Multi-OMICS for human microbiome measuring $p=200$ metabolites, and $q=800$ enzymes for $n=500$ individuals.


## Classical Estimator / Sample CCA algorithm

Just stick in sample covariances

$$
\begin{aligned}
& \underset{u \in \mathbb{R}^{\rho}, v \in \mathbb{R}^{9}}{\operatorname{maximize}} \widehat{\widehat{\operatorname{Cov}}}\left(u^{\top} \mathbf{X}, v^{\top} \mathbf{Y}\right) \\
& \text { subject to } \widehat{\operatorname{Var}}\left(u^{\top} \mathbf{X}\right) \leq 1, \widehat{\operatorname{Var}}\left(v^{\top} \mathbf{Y}\right) \leq 1, \\
& \\
& \quad \widehat{\operatorname{Cov}}\left(u^{\top} \mathbf{X}, u_{j}^{\top} \mathbf{X}\right)=\widehat{\operatorname{Cov}}\left(v^{\top} \mathbf{Y}, v_{j}^{\top} \mathbf{Y}\right)=0 \text { for } 1 \leq j \leq k-1 .
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Classical Theory: asymptotic distributions, significance tests...

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Problem: Arbitrary correlations of 1 in high dimensions $(q \geq n)$.

## Classical Estimator / Sample CCA algorithm

## Add regularisation

$$
\begin{aligned}
& \underset{u \in \mathbb{R}^{\rho}, v \in \mathbb{R}^{9}}{\operatorname{maximize}} \widehat{\widehat{\operatorname{Cov}}}\left(u^{\top} \mathbf{X}, v^{\top} \mathbf{Y}\right)-\tau_{u}\|u\|_{1}-\tau_{v}\|v\|_{1} \\
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## Setting the stage

- Main perspective: Exploratory Data Analysis (EDA) with an eye on physical interpretation. Loosely frequentist approach.
- Regularised CCA algorithms:
- ridge CCA: 12 penalty
- sparse CCA: I1 penalty
- Practical considerations:
- model / tuning parameter selection
- number of pairs to consider
- interpretation
- Unanswered question: Are these regularised CCA methods appropriate for real data? Might other structural assumptions be more natural.


## Our contributions

- New algorithm: using graphical lasso; motivated by graphical models and conditional independence.
- Practical advice: for model comparison and interpretation motivated by the fundamental geometry of population CCA.


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- Practical advice: for model comparison and interpretation motivated by the fundamental geometry of population CCA.
- Main conclusions:
- CCA is fundamentally a subspace problem
- Variates and loadings are easier to estimate than weights
- Powerful visualisation via biplots
- Model selection is subtle
- Graphical lasso approach works well!


## Our contributions

- New algorithm: using graphical lasso; motivated by graphical models and conditional independence.
- Practical advice: for model comparison and interpretation motivated by the fundamental geometry of population CCA.
- Main conclusions:
- CCA is fundamentally a subspace problem
- Variates and loadings are easier to estimate than weights
- Powerful visualisation via biplots
- Model selection is subtle
- Graphical lasso approach works well!

These may seem natural, but are far from the accepted wisdom, and should be a welcome contribution to the field.

## Questions?

wit, $3.5 \mathrm{e}+00$, range $(0,3)$ s.c.suo, $1.3 \mathrm{e}-02$, range $(0,3)$ s.c.s gglasso, $5.9 \mathrm{e}-03,[0,1]$ s.c.stidge, $1.1 \mathrm{e}-01$, range $(0,3)$ s.c.s


## Pretty picture



## Links with matrix analysis

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- Singular Value Decomposition

$$
\left(\rho_{k}, \Sigma_{x}^{1 / 2} u_{k}, \Sigma_{y}^{1 / 2} v_{k}\right) \text { give SVD of } M:=\Sigma_{x x}^{-1 / 2} \Sigma_{x y} \Sigma_{y y}^{-1 / 2}
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- Generalised Eigenvalue Problem: $A w=\lambda B w$

$$
A=\left(\begin{array}{cc}
0 & \Sigma_{X Y} \\
\Sigma_{Y X} & 0
\end{array}\right), \quad B=\left(\begin{array}{cc}
\Sigma_{X X} & 0 \\
0 & \Sigma_{Y Y}
\end{array}\right), \quad w=\binom{u}{v}, \quad d=p+q .
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- Canonical Angles

$$
\begin{aligned}
& \mathcal{X}:=\operatorname{span}\left(\left\{X_{j}: j=1, \ldots, p\right\}\right), \mathcal{Y}:=\operatorname{span}\left(\left\{Y_{j}: j=1, \ldots, q\right\}\right) \text { then CCA is } \\
& \operatorname{maximize}_{W_{k} \in \mathcal{X}, Z_{k} \in \mathcal{Y}}\left\langle W_{k}, Z_{k}\right\rangle \\
& \text { subject to }\left\|W_{k}\right\|_{2} \leq 1,\left\|Z_{k}\right\|_{2} \leq 1, \\
& \quad\left\langle W_{k}, W_{j}\right\rangle=\left\langle Z_{k}, Z_{j}\right\rangle=0 \text { for } 1 \leq j \leq k-1 .
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## Probabilistic CCA

Consider the model:

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\begin{array}{rlrl}
Z & \sim \mathcal{N}\left(0, I_{d}\right), & \min (p, q) \geq d \geq 1 \\
X \mid Z & \sim \mathcal{N}\left(W_{1} Z+\mu_{1}, \Psi_{1}\right), & W_{1} \in \mathbb{R}^{p \times d}, \Psi_{1} \succcurlyeq 0 \\
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\end{array}
$$

Then the MLEs of the parameters $W_{1}, W_{2}, \Psi_{1}, \Psi_{2}, \mu_{1}, \mu_{2}$ are

$$
\begin{aligned}
& \hat{W}_{1}=\hat{\Sigma}_{x x} U_{d} M_{1} \\
& \hat{W}_{2}=\hat{\Sigma}_{y y} V_{d} M_{2} \\
& \hat{\Psi}_{1}=\hat{\Sigma}_{x x}-\hat{W}_{1} \hat{W}_{1}^{T} \\
& \hat{\Psi}_{2}=\hat{\Sigma}_{y y}-\hat{W}_{2} \hat{W}_{2}^{T}
\end{aligned}
$$

and $\hat{\mu_{1}}=\bar{X}, \hat{\mu_{2}}=\bar{Y}$ where $M_{1}, M_{2} \in \mathbb{R}^{d \times d}$ are arbitrary matrices with $M_{1} M_{2}^{T}=R,\left\|M_{1}\right\| \leq 1,\left\|M_{2}\right\| \leq 1$

## Graphical Models

- Setup: $X=\left(X^{1}, \ldots, X^{p}\right)$ a random vector; $G=(V, E)$ graph with $V=\{1, \ldots, p\}$
- Key idea: graph structure constrains distribution of $X$
- Gaussian graphical models: $X^{i} \perp X^{j} \mid\left(X^{k}\right)_{k \neq i, j}$ whenever $(i, j) \notin E$



## Graphical Lasso

- Aim: Solve structure estimation problem
- Setup: samples $x_{1}, \ldots, x_{n}$ from some zero-mean Gaussian with precision matrix $\in \mathbb{R}^{p \times p}$
- Write: $\mathbf{S}=\frac{1}{n} \sum_{i=1}^{n} x_{i} x_{i}^{T} \in \mathbb{R}^{p \times p}$
- Log-likelihood:

$$
I(\Omega ; \mathbf{X})=\log \operatorname{det}-\operatorname{trace}(\mathbf{S})
$$

- Penalised Objective:

$$
{ }^{\wedge} \in \operatorname{argmax}_{\succeq 0}\left\{\log \operatorname{det}-\operatorname{trace}(\mathbf{S})-\alpha \rho_{1}()\right\}
$$

where: $\alpha \in(0, \infty)$ is a penalty parameter, $\rho_{1}()=\sum_{i \neq j}\left|\Omega_{i j}\right|$

## Our Approach

## Observations:

- $\Sigma=\Omega^{-1}$ is differentiable function of $\Omega$.
- $M$ is a differentiable function of $\Sigma$
- So $M=f(\Omega)$ where $f$ is differentiable

Algorithm: Estimate $\Omega$ with graphical lasso, plug-in $\hat{M}=f(\hat{\Omega})$, then apply SVD

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Theorem: can combine results in the literature to see convergence rate

$$
\sin \Theta(\hat{B}, B) \lesssim s_{0}(p)\left(\frac{\log p}{n}\right)^{1 / 2}
$$

## Existing Methods: PMD [WTH09]

Penalised Matrix Decomposition A natural but difficult objective:

$$
\begin{aligned}
& \underset{u \in \mathbb{R}^{\rho}, v \in \mathbb{R}^{G}}{\operatorname{maximize}} \frac{1}{n} u^{T} \mathbf{X}^{T} \mathbf{Y}_{v} \\
& \text { subject to } \frac{1}{n}\|\mathbf{X} u\|_{2}^{2} \leqslant 1, \quad \frac{1}{n}\|\mathbf{Y} v\|_{2}^{2} \leqslant 1, \quad\|u\|_{1} \leqslant c_{1},\|v\|_{1} \leqslant c_{2}
\end{aligned}
$$

Make constraints tractable:

$$
\begin{aligned}
& \underset{u \in \mathbb{R}^{P}, v \in \mathbb{R}^{q}}{\operatorname{maximize}} \frac{1}{n} u^{T} \mathbf{X}^{T} \mathbf{Y}_{v} \\
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Justification: Identity approximation valid
Algorithm: alternate between solving for $u, v$ by soft-thresholding

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$$

Justification: Identity approximation valid
Algorithm: alternate between solving for $u, v$ by soft-thresholding
Later pairs: Apply with $\frac{1}{n} \mathbf{X}^{T} \mathbf{Y}-\sum_{j=1}^{k-1} d_{j} u_{j} v_{j}^{T}$

## Existing Methods: AMA [SMN+17]

Alternating Minimisation Algorithm
Use Lagrange multiplier penalty rather than explicit constraints:

$$
\begin{aligned}
\underset{u, v}{\operatorname{minimize}}-\frac{1}{n} u^{T} \mathbf{X}^{T} \mathbf{Y} v & +\tau_{1}\|u\|_{1}+\tau_{2}\|v\|_{1} \\
& +\mathbb{1}\left\{u: \frac{1}{n}\|\mathbf{X} u\|_{2}^{2} \leq 1\right\}+\mathbb{1}\left\{v: \frac{1}{n}\|\mathbf{Y} v\|_{2}^{2} \leq 1\right\}
\end{aligned}
$$

Algorithm: alternate between solving for $u, v$. For $v$ fixed get:

$$
\operatorname{minimize}_{u \in \mathbb{R}^{p}, z \in \mathbb{R}^{n}}^{-u^{T} \mathbf{X}^{T} \mathbf{Y} v+\tau_{1}\|u\|_{1}}+\underbrace{\mathbb{1}\left\{\|z\|_{2} \leq 1\right\}}_{f(u)}
$$

subject to $\mathbf{X} u=z$
Tool: Linearized ADMM

## Existing Methods: AMA [SMN+17]

Alternating Minimisation Algorithm
Use Lagrange multiplier penalty rather than explicit constraints:

$$
\begin{aligned}
\underset{u, v}{\operatorname{minimize}}-\frac{1}{n} u^{T} \mathbf{X}^{T} \mathbf{Y} v & +\tau_{1}\|u\|_{1}+\tau_{2}\|v\|_{1} \\
& +\mathbb{1}\left\{u: \frac{1}{n}\|\mathbf{X} u\|_{2}^{2} \leq 1\right\}+\mathbb{1}\left\{v: \frac{1}{n}\|\mathbf{Y} v\|_{2}^{2} \leq 1\right\}
\end{aligned}
$$

Algorithm: alternate between solving for $u, v$.
For $v$ fixed get:

$$
\operatorname{minimize}_{u \in \mathbb{R}^{p}, z \in \mathbb{R}^{n}}^{-u^{T} \mathbf{X}^{T} \mathbf{Y} v+\tau_{1}\|u\|_{1}}+\underbrace{\mathbb{1}\left\{\|z\|_{2} \leq 1\right\}}_{f(u)}
$$

subject to $\mathbf{X} u=z$
Tool: Linearized ADMM
Later pairs: Add constraint $U^{T} \mathbf{X}^{T} \mathbf{X} u=0 ; V^{T} \mathbf{Y}^{T} \mathbf{Y} v=0$

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