

Multi-Objective Optimisation Techniques in Reservoir Simulation

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Outline

- Introduction
- Stochastic Optimisation
- Model Calibration
- Forecasting
- Reservoir Optimisation
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Mathematics of Flow in Porous Media

- Conservation of Mass
- Conservation of Momentum
 - replaced by Darcy's law

$$\mathbf{v} = -\frac{k(\mathbf{x})}{\mu} \nabla p$$

- Conservation of Energy
 - most processes isothermal
- Equation of State

Equations governing flow

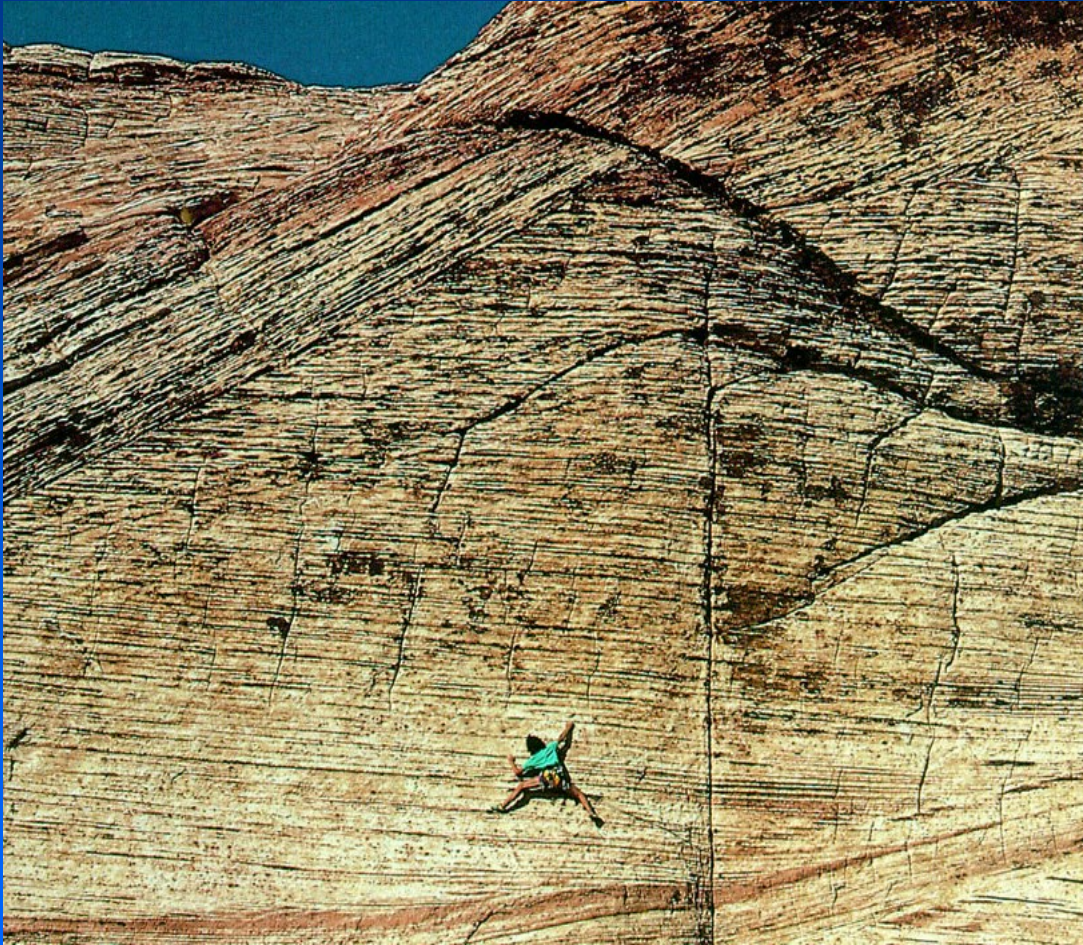
- Parabolic equation for pressure

$$c \frac{\partial p}{\partial t} = \nabla \cdot \left(k(\mathbf{x}) \left(\frac{k_{ro}(S)}{\mu_o} + \frac{k_{rw}(S)}{\mu_w} \right) \nabla p \right)$$

- Hyperbolic equation for saturation

$$\phi(\mathbf{x}) \frac{\partial (\rho_o x_i S_o + \rho_g y_i S_g)}{\partial t} + \nabla \cdot (\rho_o x_i \mathbf{v}_o + \rho_g y_i \mathbf{v}_g) = 0$$

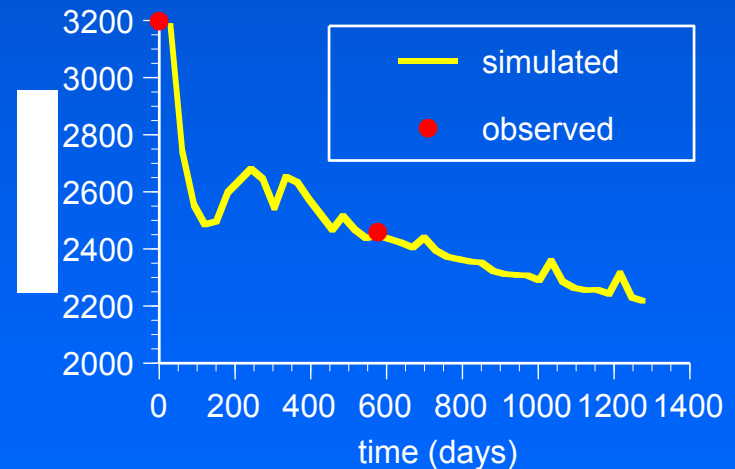
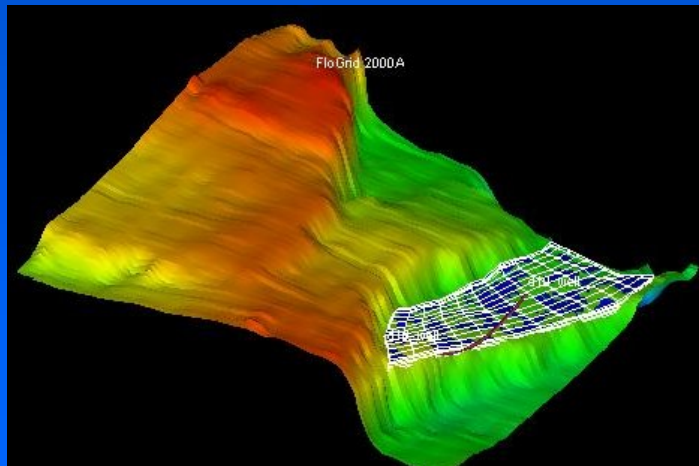
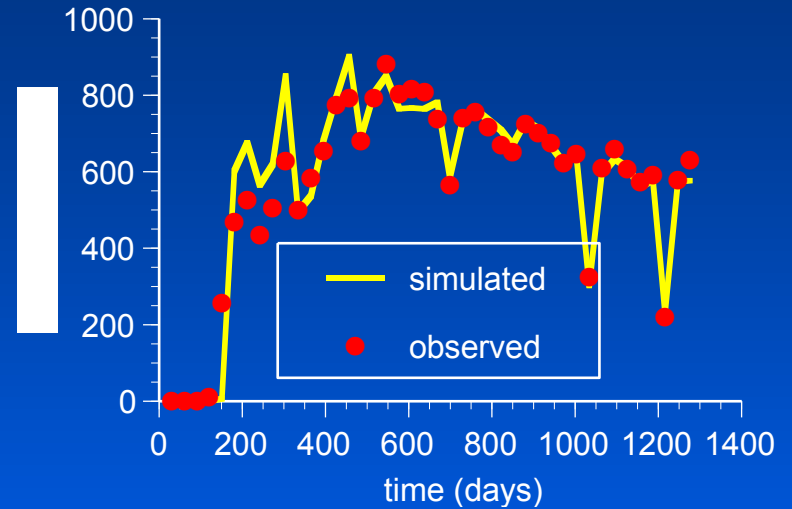
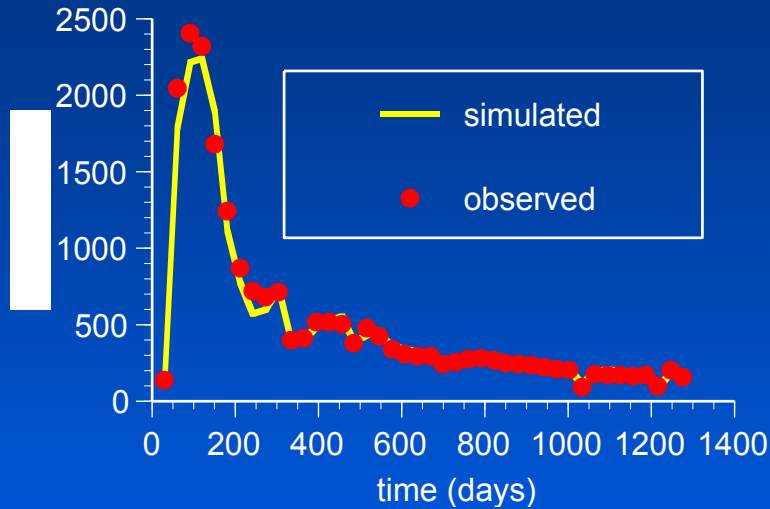
Data Collection



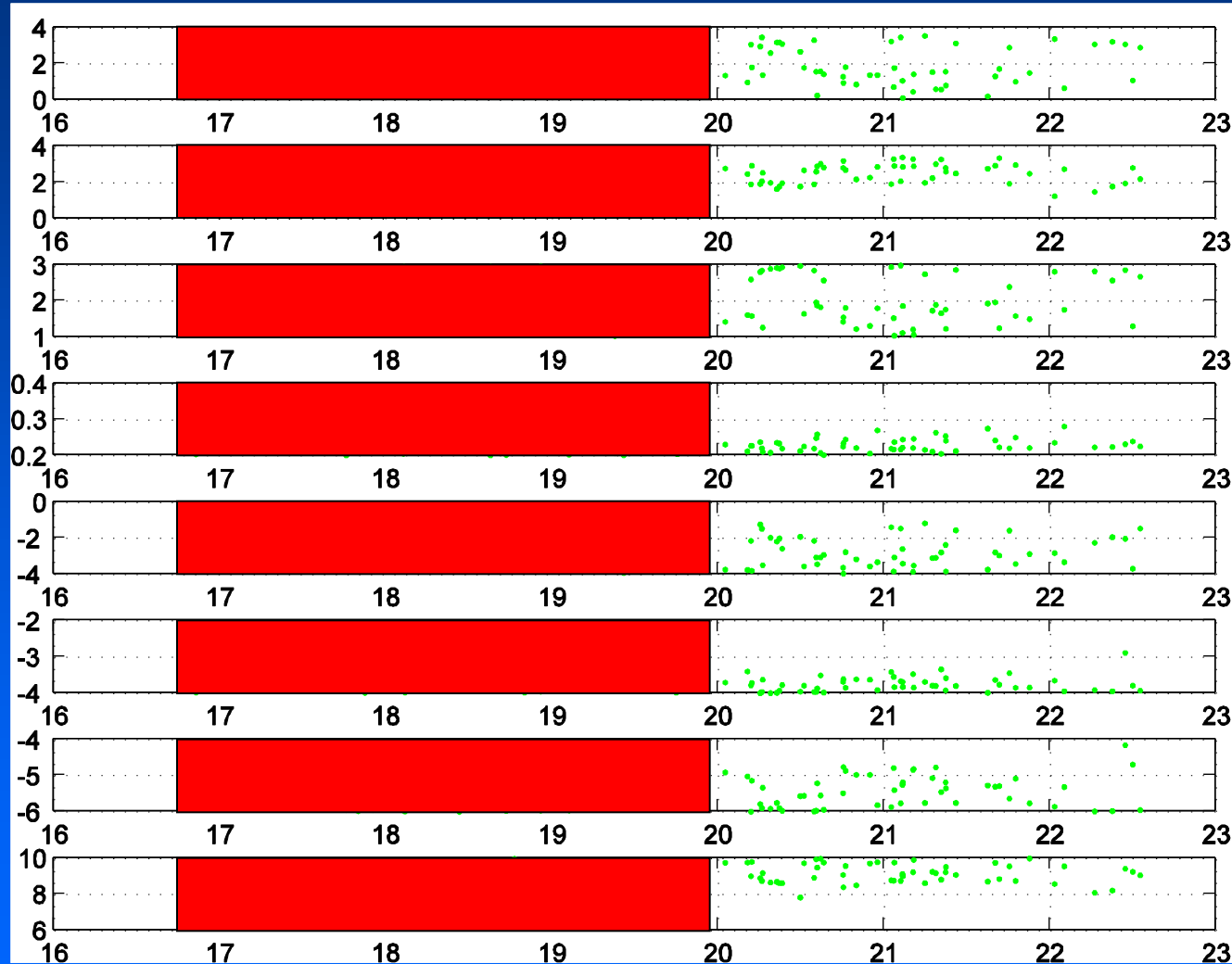
$$\phi(\mathbf{x}) = ?$$

$$k(\mathbf{x}) = ?$$

Model Calibration: Teal South



Range of Possible Values for Unknown Parameters



$\log(kh_1)$

$\log(kh_2)$

boundary

porosity

$\log(kv/kh_1)$

$\log(kv/kh_1)$

$\log(c_r)$

aquifer
strength

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Particle Swarm Optimization (PSO)

- A swarm intelligence algorithm (Kennedy & Eberhart, 1995).
- Particles are points in parameter space.
- Particles move based on their own experience and that of the swarm.
- PSO equations

$$\mathbf{v}_i^{k+1} = \omega \mathbf{v}_i^k + c_1 r_1 \left(\mathbf{p}_i^{best} - \mathbf{x}_i^k \right) + c_2 r_2 \left(\mathbf{g}_{best}^k - \mathbf{x}_i^k \right)$$

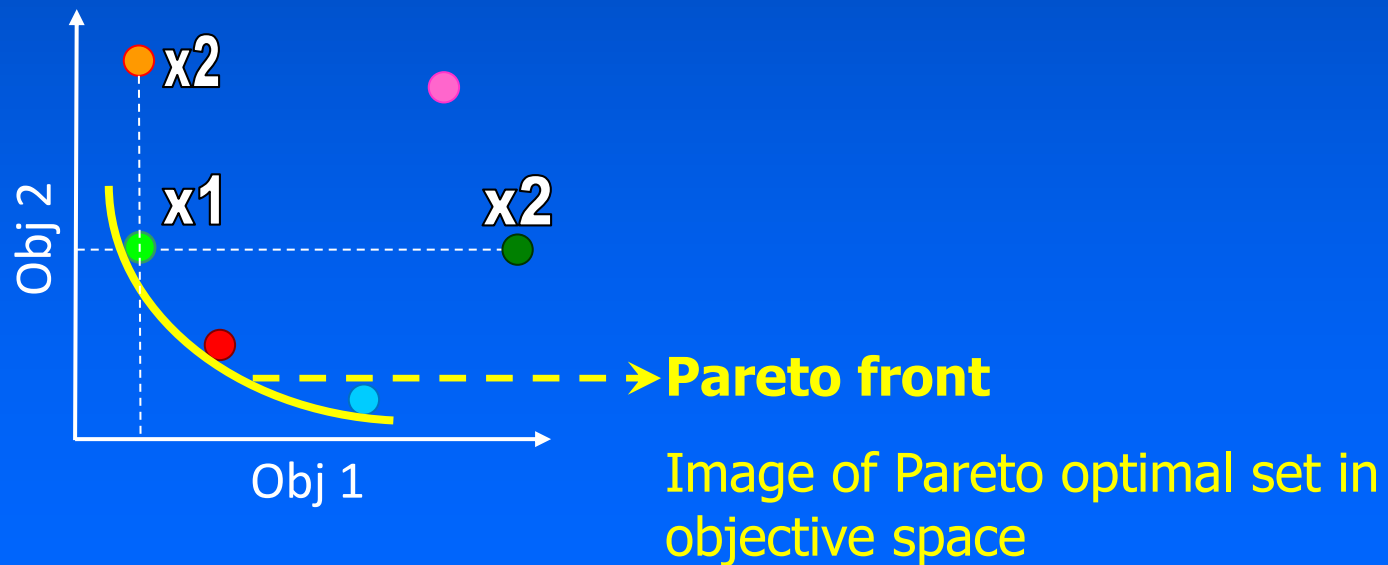
$$\mathbf{x}_i^{k+1} = \mathbf{x}_i^k + \mathbf{v}_i^{k+1}$$

- r_1, r_2 are random vectors
- ω is the inertial weight
- c_1, c_2 are the cognition and social acceleration components

Dominance and Pareto Optimality

Solution x_1 dominates solution x_2 , if :

1. x_1 is no worse than x_2 in all objectives, and
2. x_1 is strictly better than x_2 in at least one objective



MO Particle Swarm Optimization (PSO)

- MOPSO equations

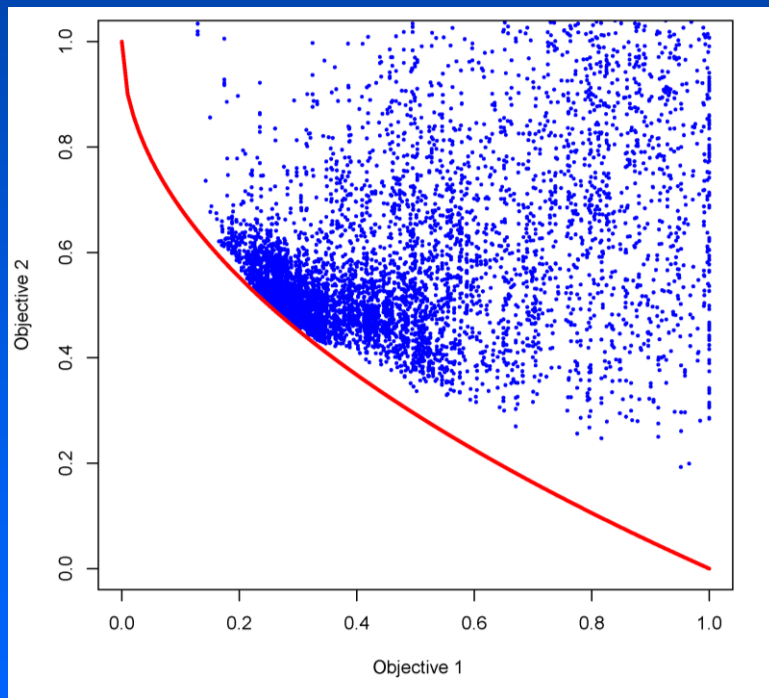
$$v_i^{k+1} = \omega v_i^k + c_1 r_1 (p_i^{best} - x_i^k) + c_2 r_2 (g_{best}^k - x_i^k)$$

$$x_i^{k+1} = x_i^k + v_i^{k+1}$$

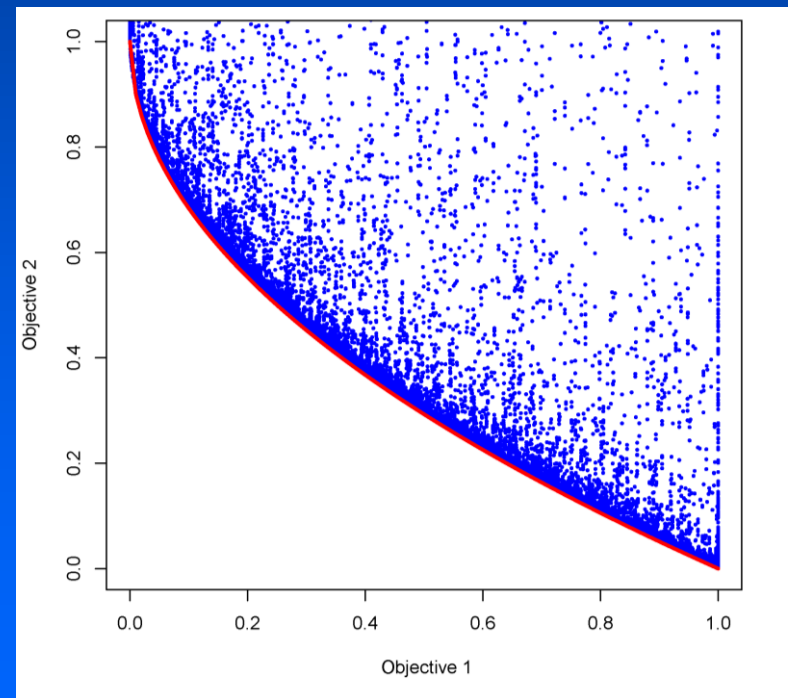
- r_1, r_2 are random vectors
- ω is the inertial weight
- c_1, c_2 are the cognition and social acceleration components
- Pbest and Gbest now sampled from Pareto archive

Why Use Multi-Objective?

- Sum of objectives – limited exploration of Pareto front
 - Example minimising two objectives



Objective sum



Multi-Objective

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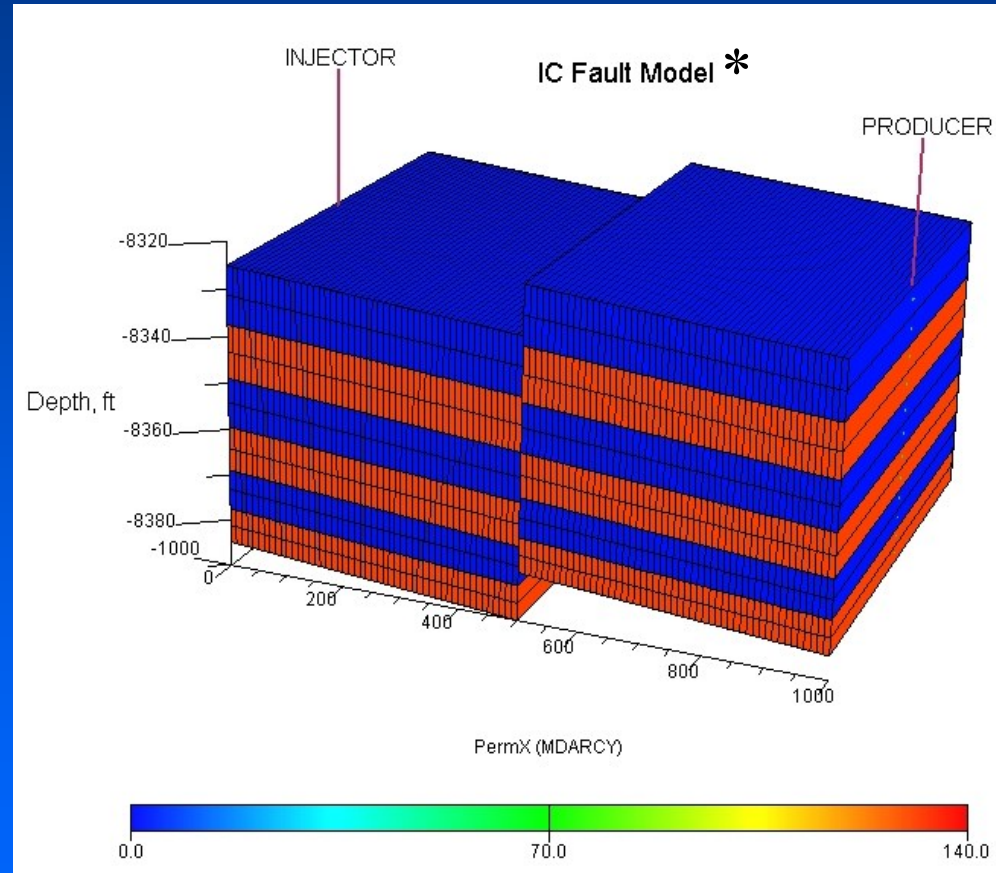
Model Calibration

- Called 'History Matching' in oil business
- Synthetic example
 - IC Fault Model
- Real example
 - Zagadka Field

IC Fault Model

- Synthetic 2D Model
- 2 Wells: 1 Inj, 1 Prod
- 6 Layers
- 1,3,5 Poor Sand (blue)
- 2,4,6 Good Sand (red)
- 1 Fault

- 3 Uncertain Inputs:
 1. $k_{\text{high}} = [100,200]$ mD
 2. $k_{\text{low}} = [0,50]$ mD
 3. $\text{throw} = [0,60]$ ft



* Data from Z. Tavassoli, Jonathan N. Carter, and Peter R. King, Imperial College, London

IC Fault Model

Observed

$$k_{\text{high}} = 131.6 \text{ mD}$$

$$k_{\text{low}} = 1.3 \text{ mD}$$

$$\text{throw} = 10.4 \text{ ft}$$

Misfit Definition:

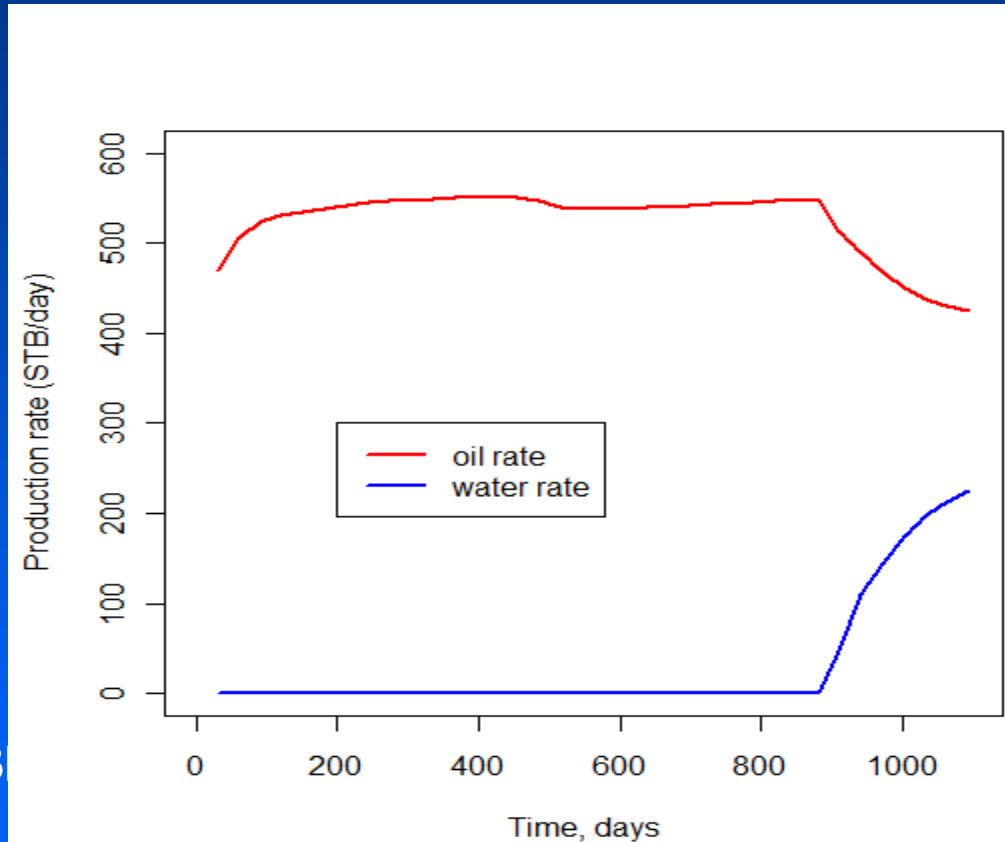
$$M = \frac{1}{n} \sum_p \sum_t \frac{(\text{sim} - \text{obs})^2}{2\sigma^2}$$

$$\sigma = 0.03 \times \text{obs}$$

p : oil/water rates

- Simulator controlled to match B the wells

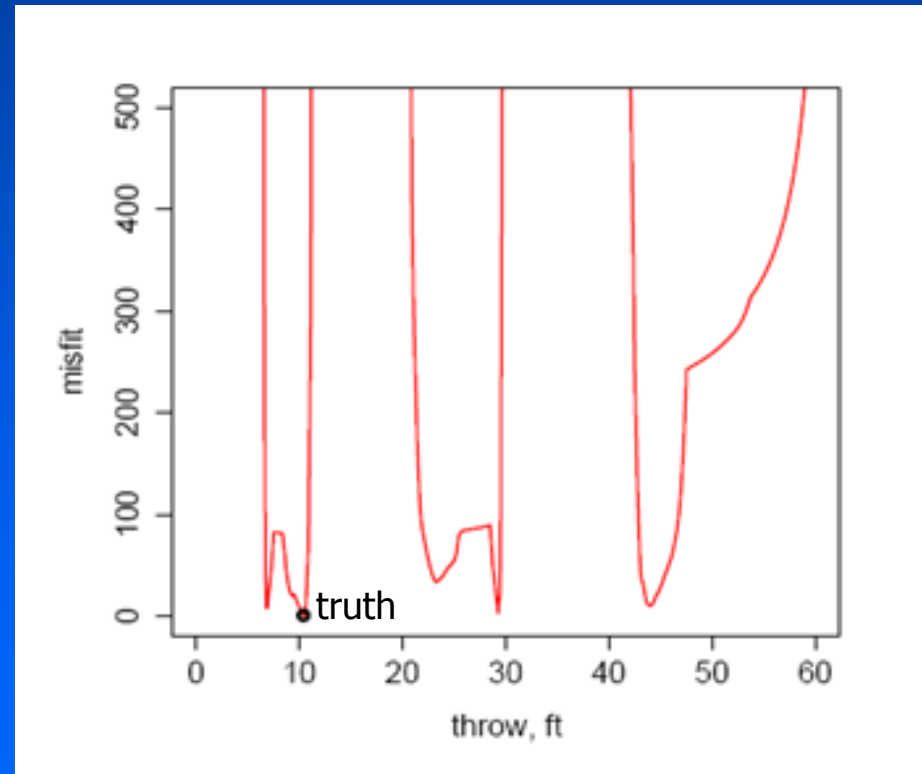
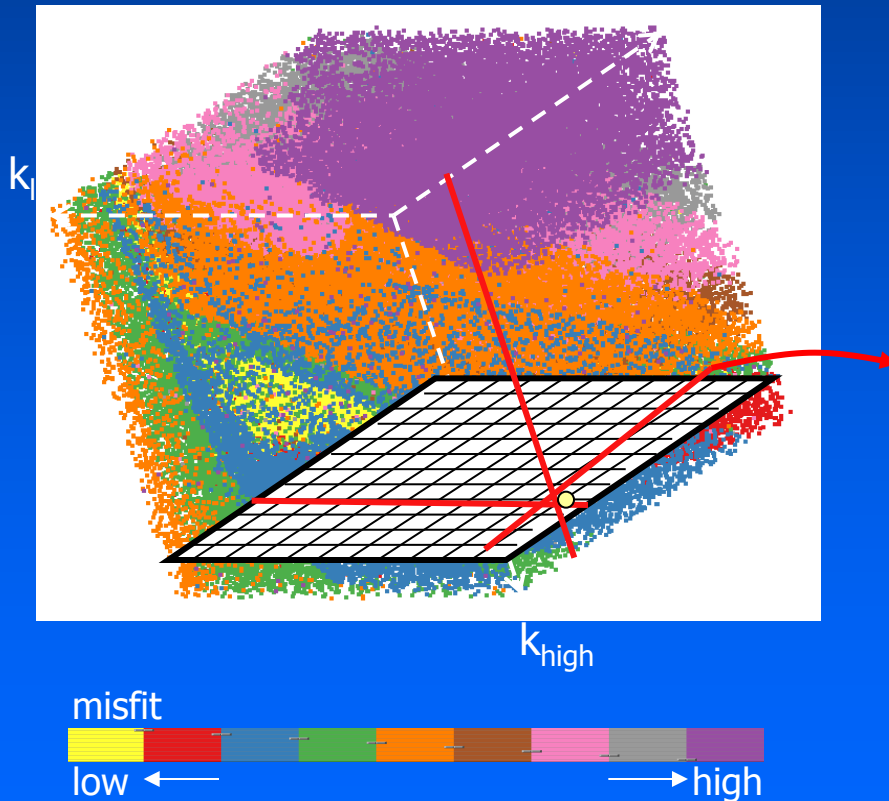
Truth Profile (Observed)



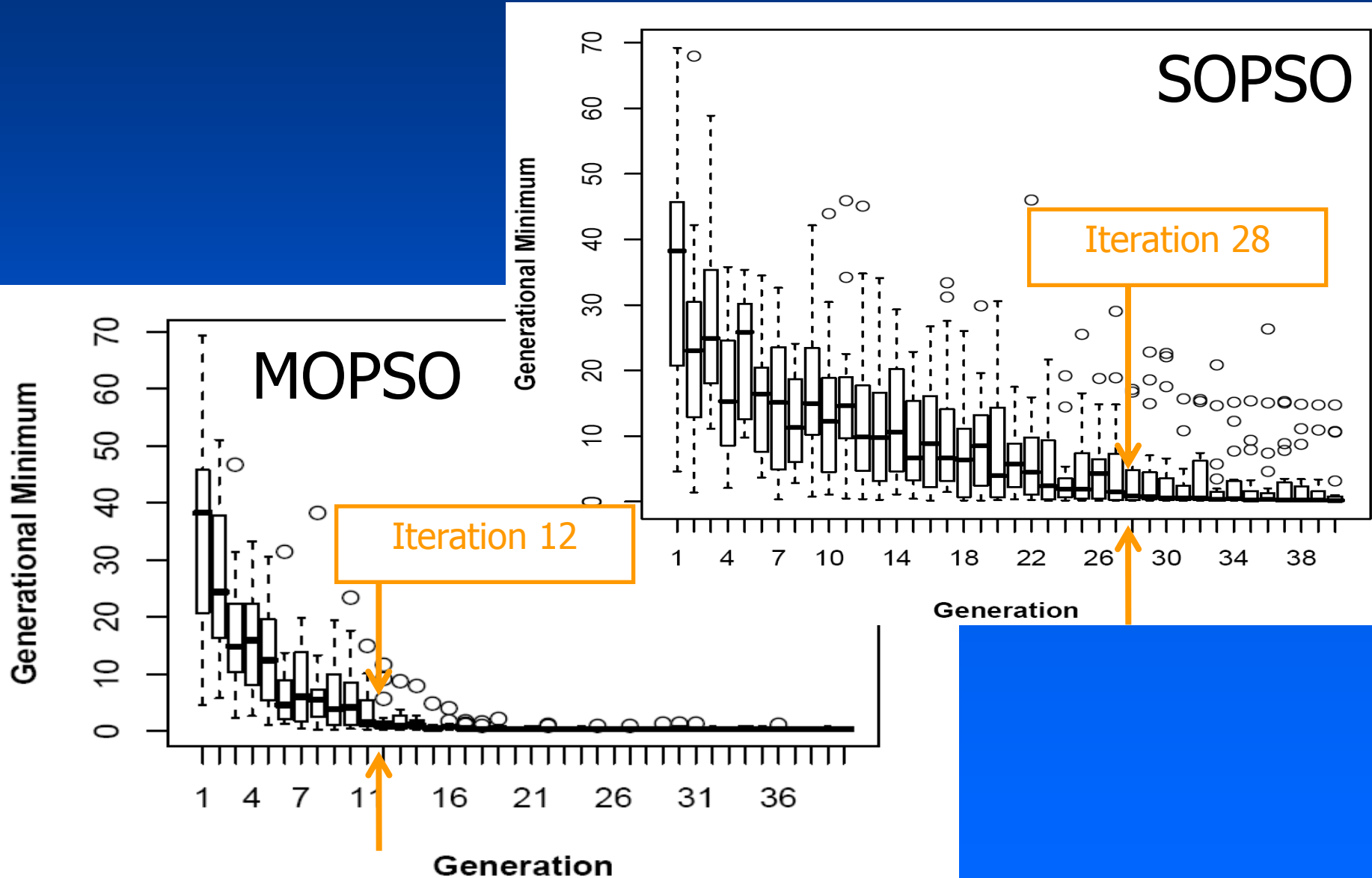
IC Fault Model Misfit Surface

Database (DB)

159,661 uniformly generated models

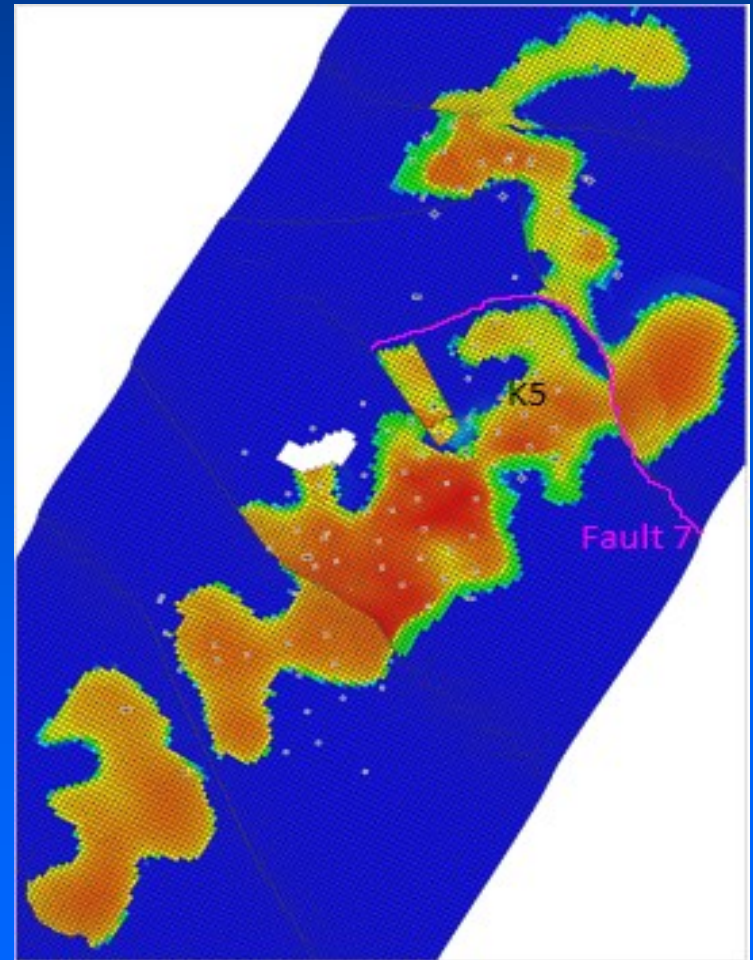


Convergence Speed – 20 Runs

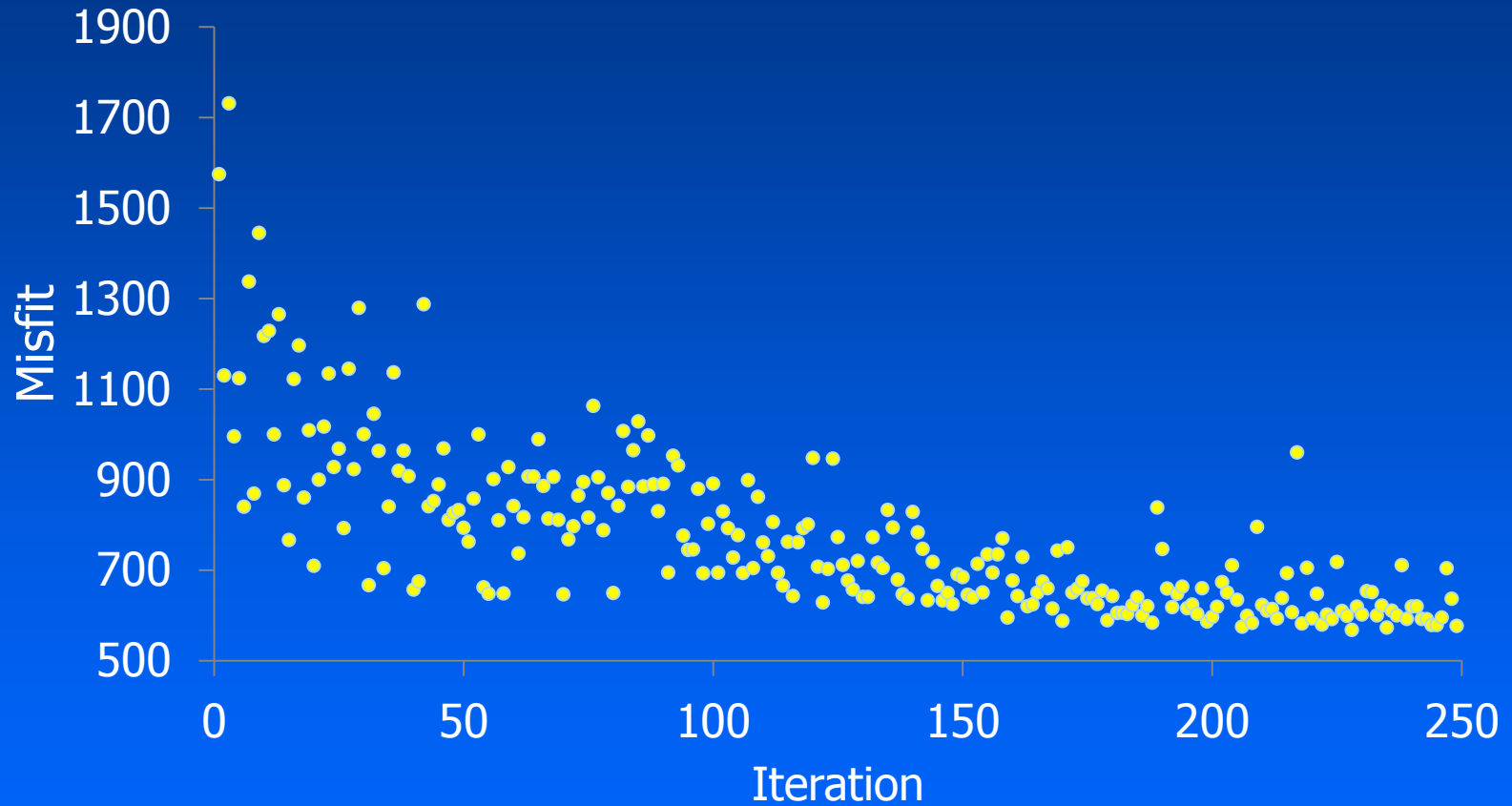


Zagadka Field

- Waterflood/aquifer support
- 95 wells in 10 groups
- 15 years history
- Compartmentalized

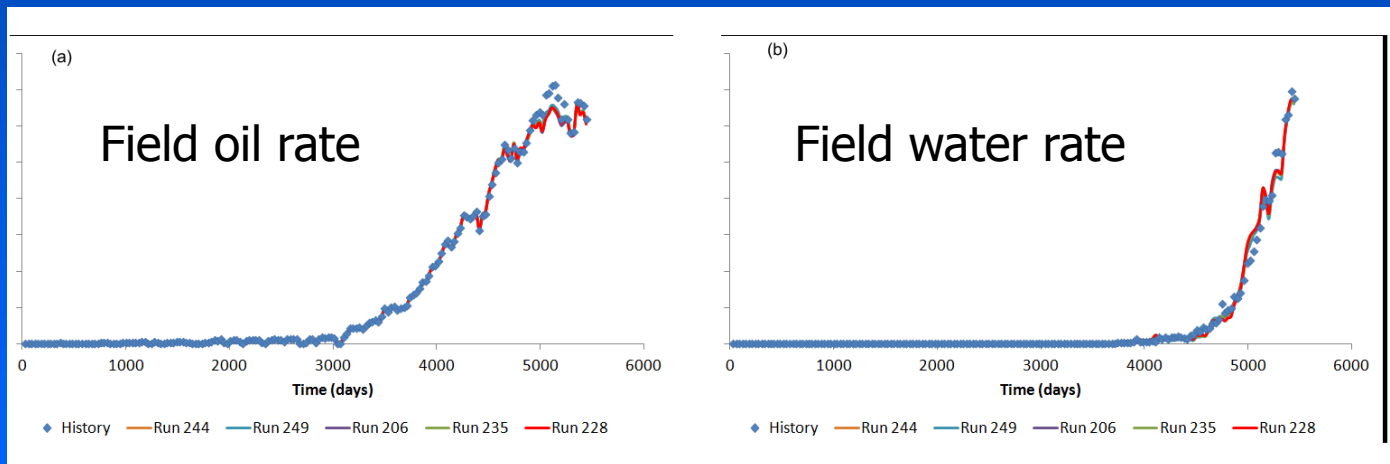


Model 4 Convergence (PSO)

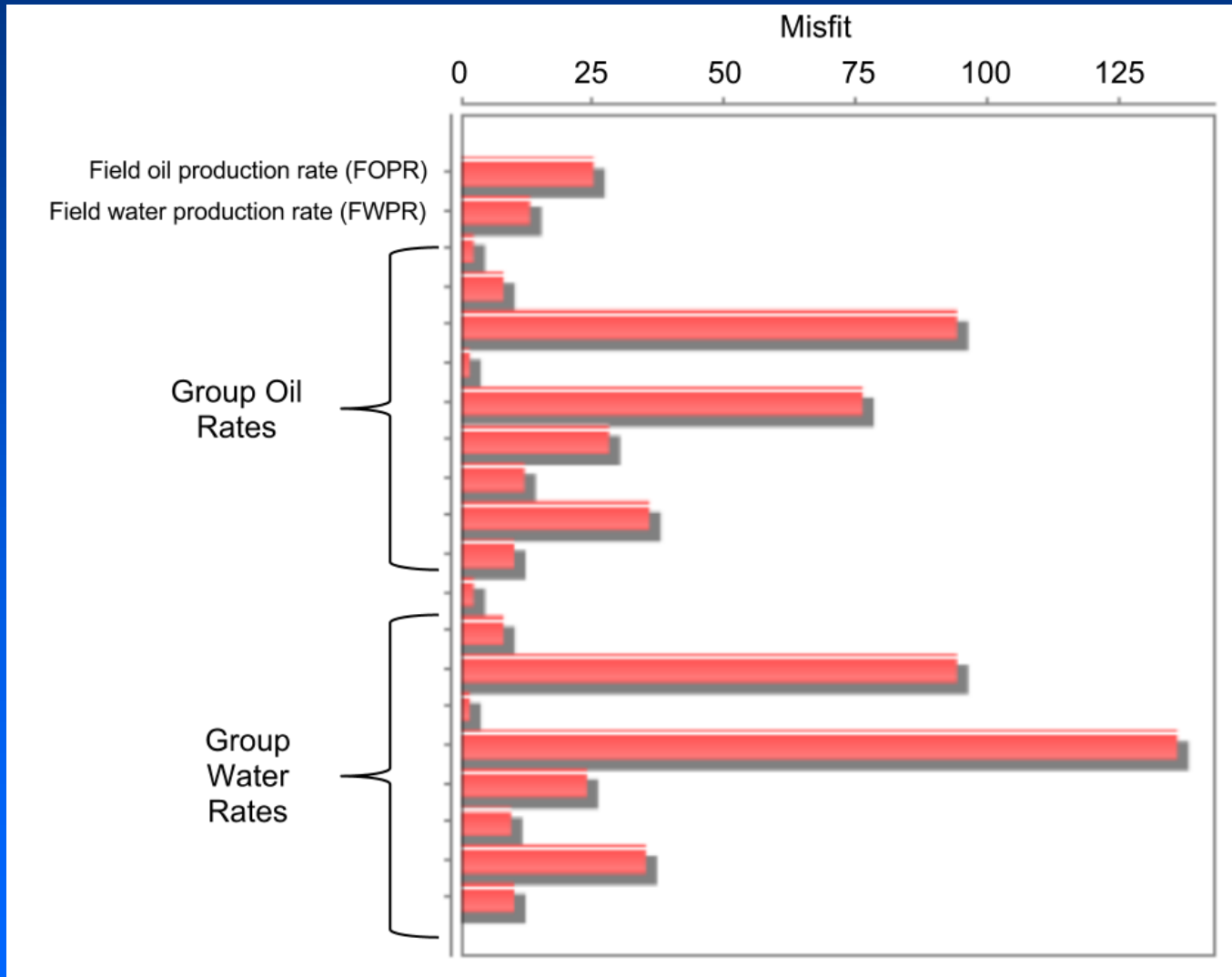


Model 4 Field Level History Match

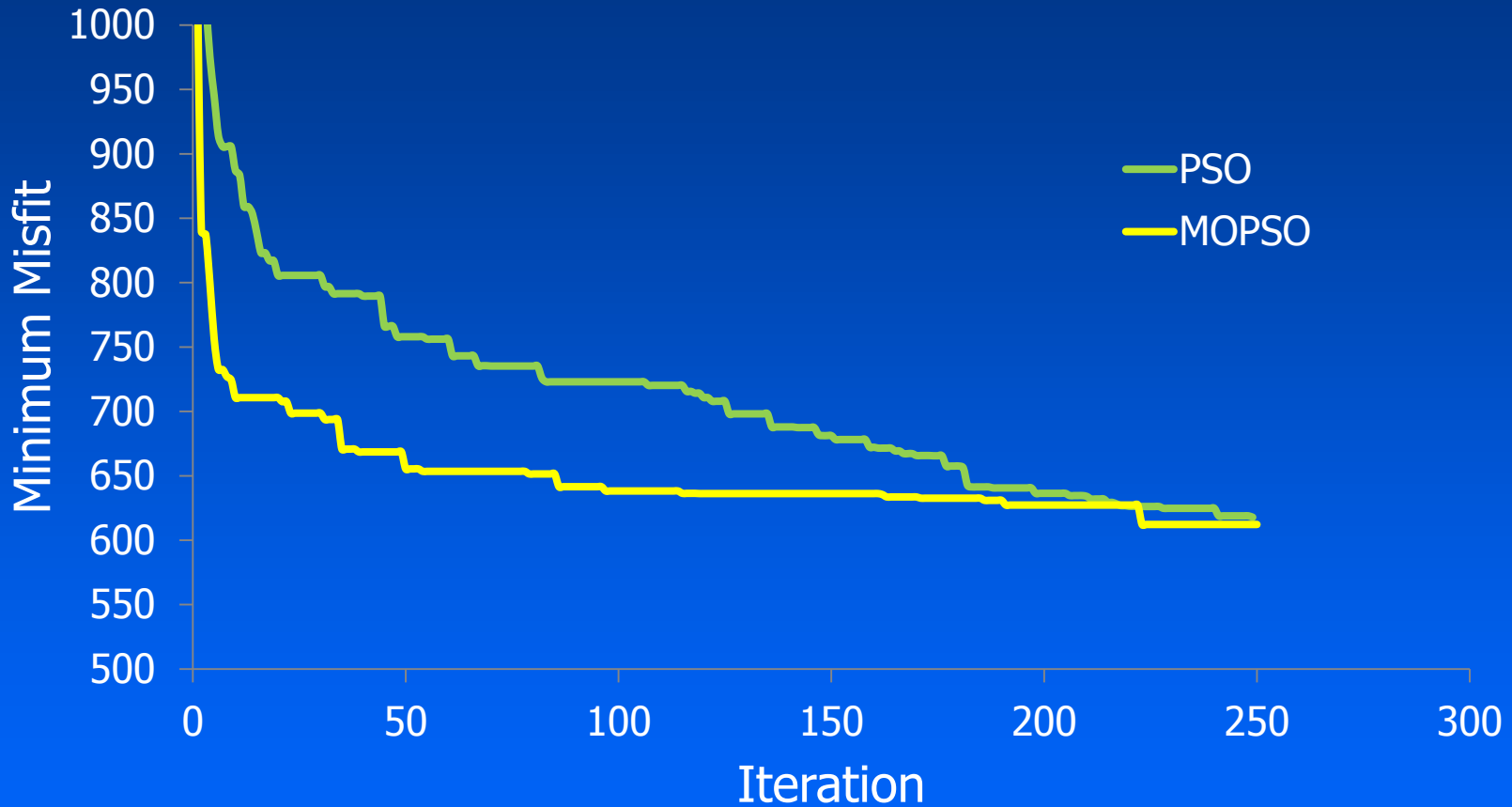
- Match with PSO (single objective)
- 250 simulations (overnight, 12 core workstation)



Match on Group Rates – Single Objective

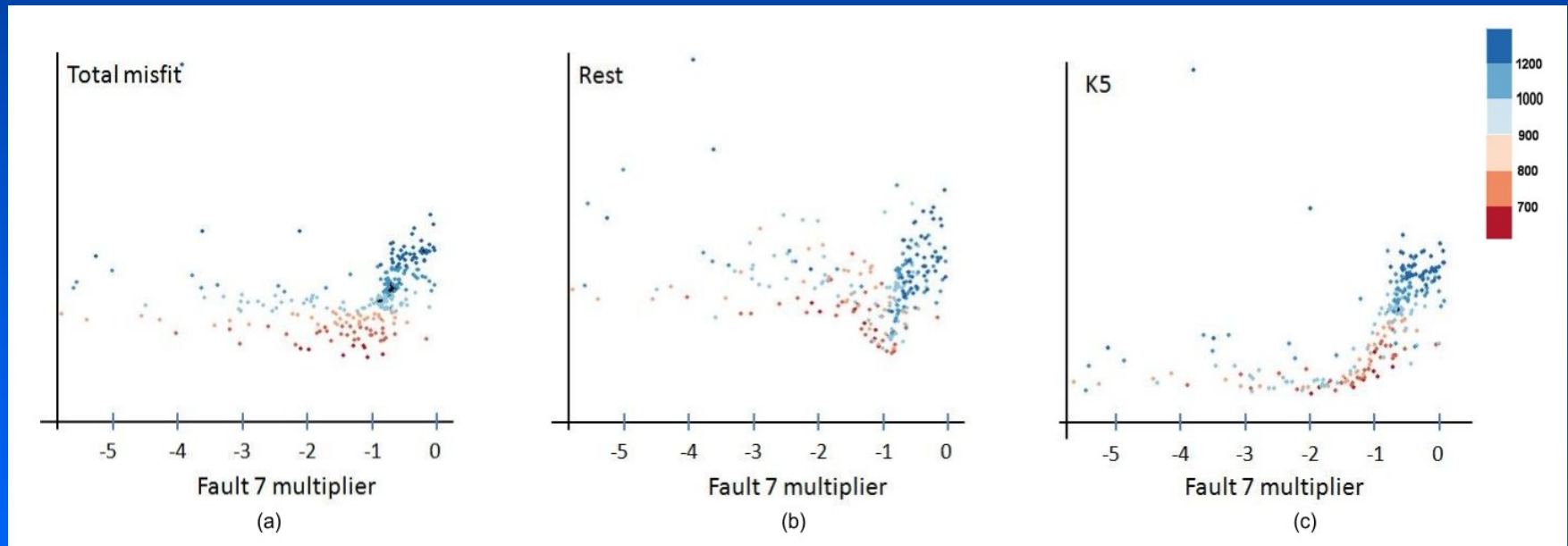


Multi-Objective vs Single Objective



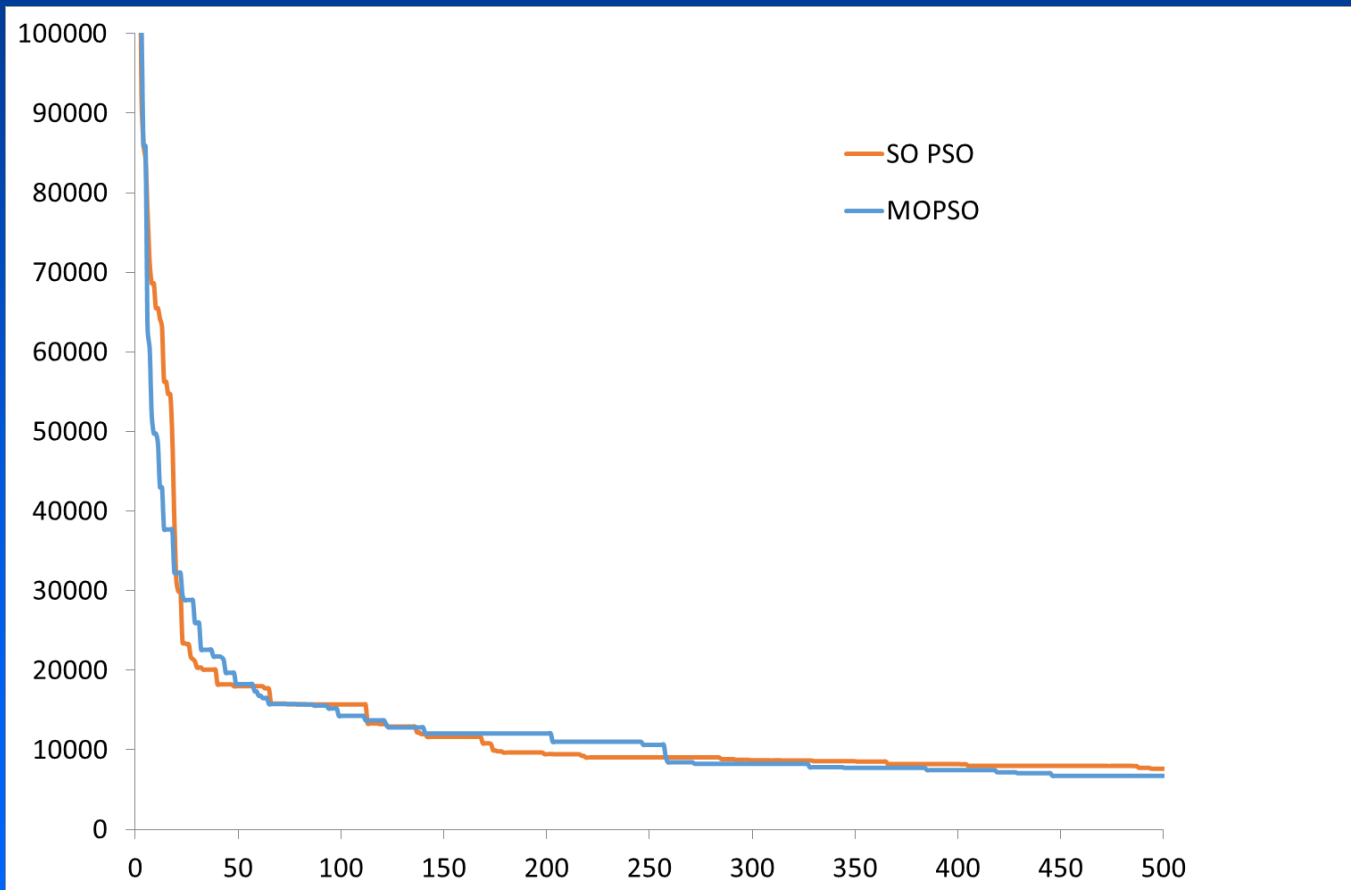
Multi-Objective Trade Off

- MO balances changes to fit one quantity vs another

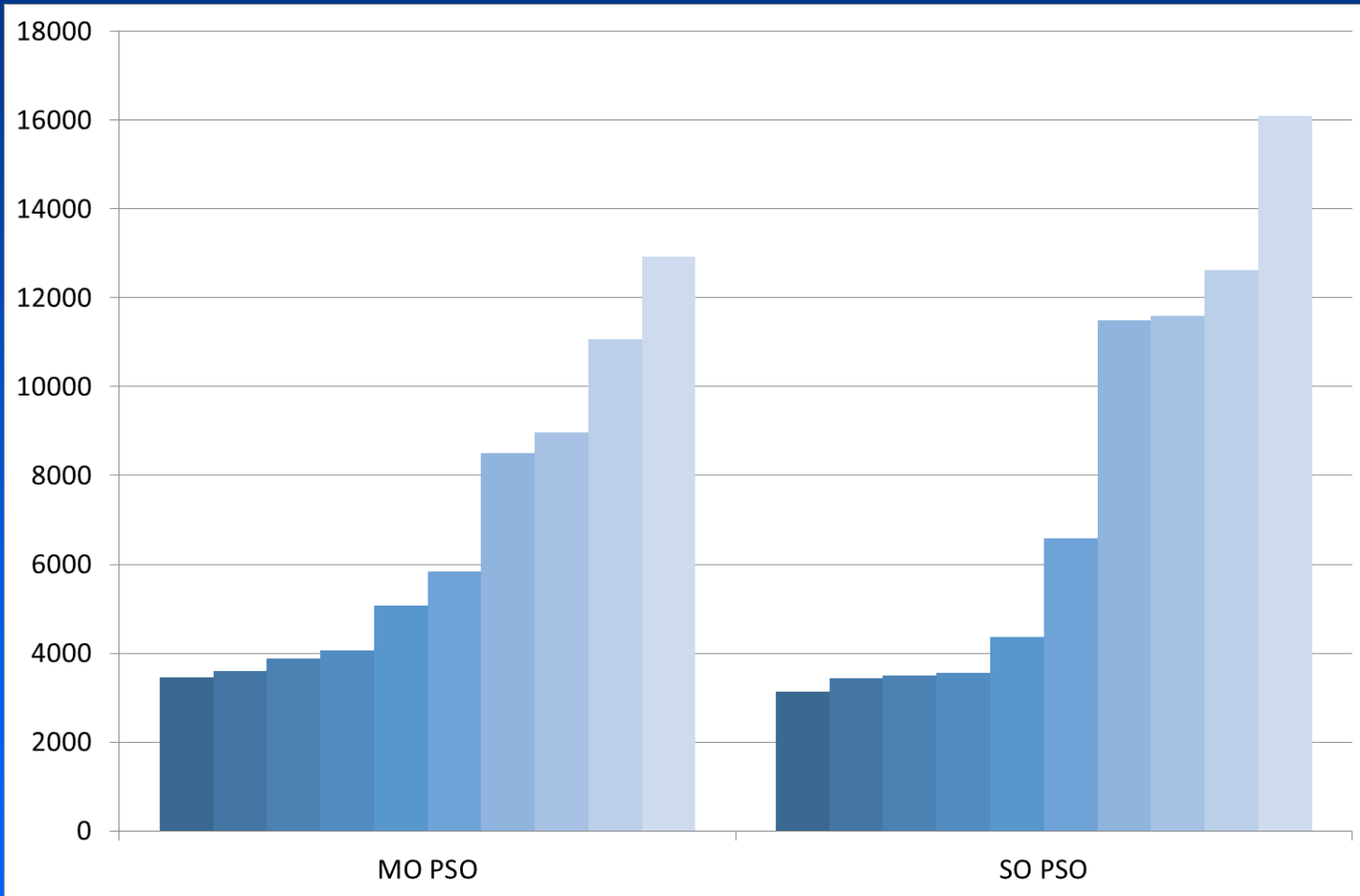


MO Not Always Faster than SO

- Study on EoN field



Histogram of 10 Final Misfits



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Forecasting with MO

- Generic Bayesian integral

$$J = \int g(\mathbf{m})P(\mathbf{m})d\mathbf{m}$$

eg mean oil rate = $\int Q_o(\mathbf{m})P(\mathbf{m})d\mathbf{m}$

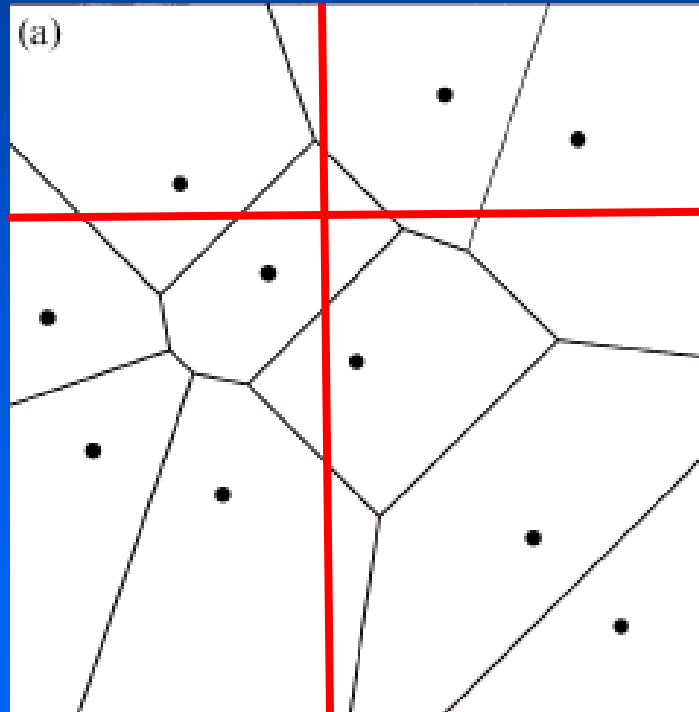
- MC approximation

$$J = \frac{1}{N} \sum_{k=1}^N \frac{g(\mathbf{m}_k)P(\mathbf{m}_k)}{h(\mathbf{m}_k)} = \frac{1}{N} \sum_{k=1}^N g(\mathbf{m}_k)P(\mathbf{m}_k)dV_k$$

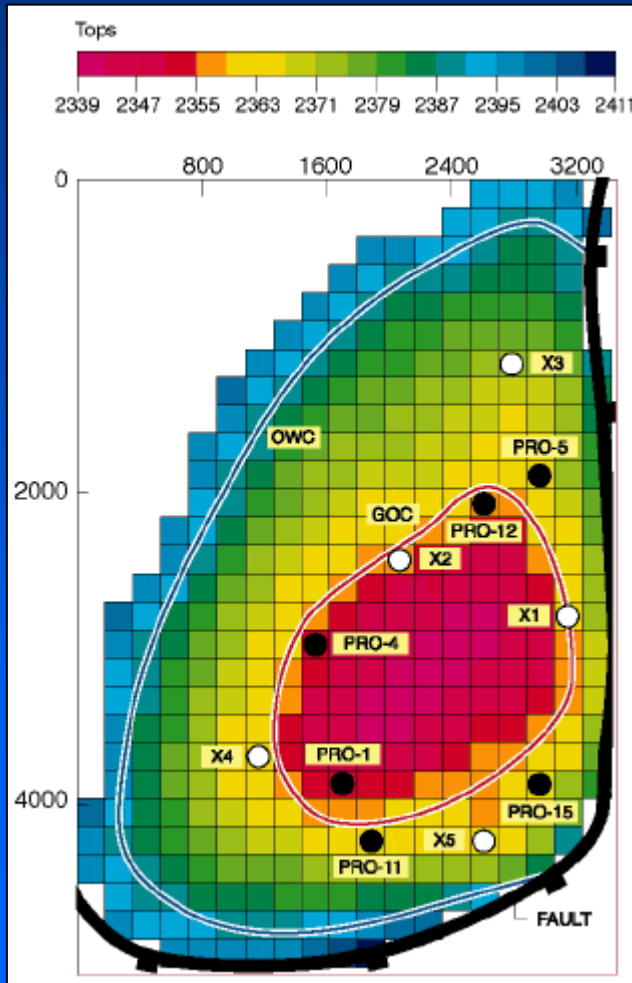
- Resample to calculate $P(\mathbf{m}_k)dV_k$

Calculating Weights for Sample

- Gibbs sampler
 - Assume misfit constant in Voronoi cell



Single & Multi Objective HM for PUNQ-S3



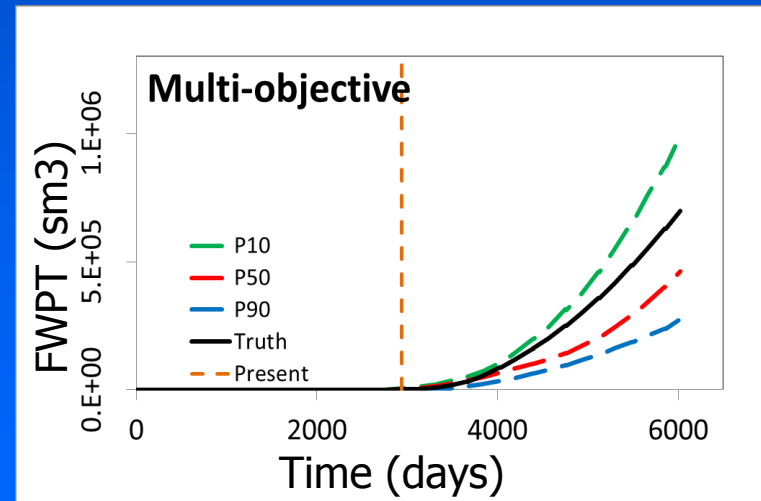
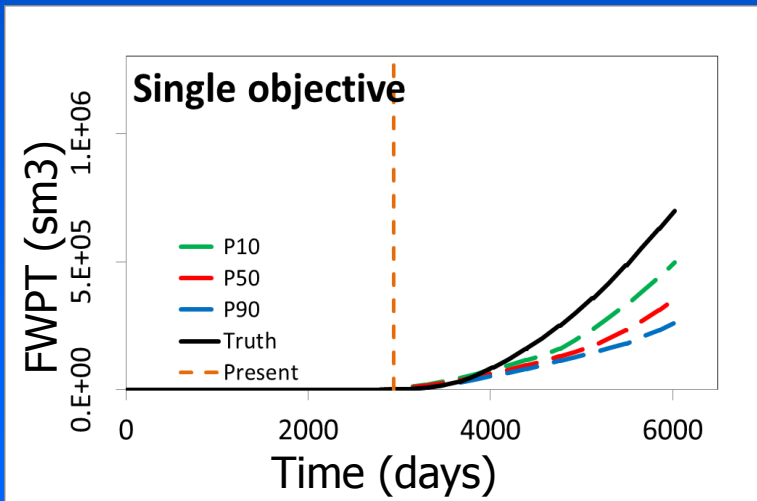
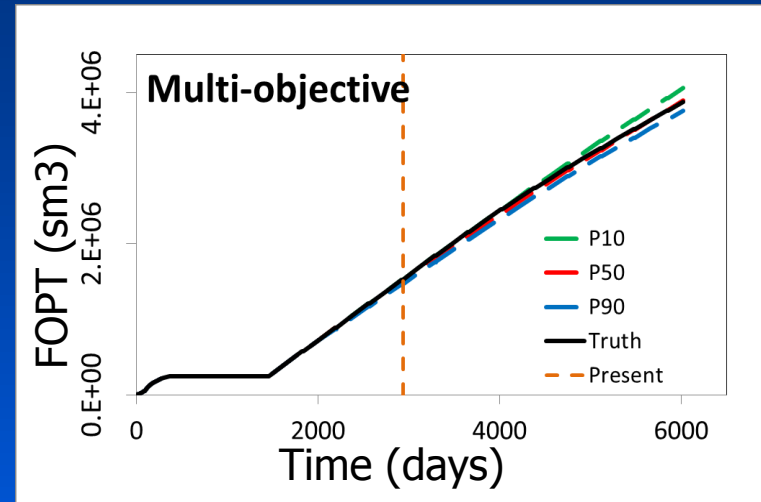
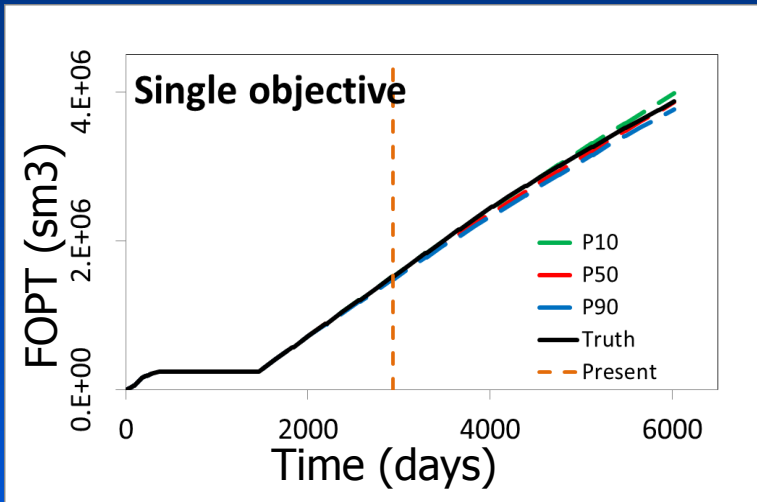
Based on real field

An industry standard benchmark

Multiple wells and production variables

Algorithm used: PSO

SO vs. MO – Forecasting



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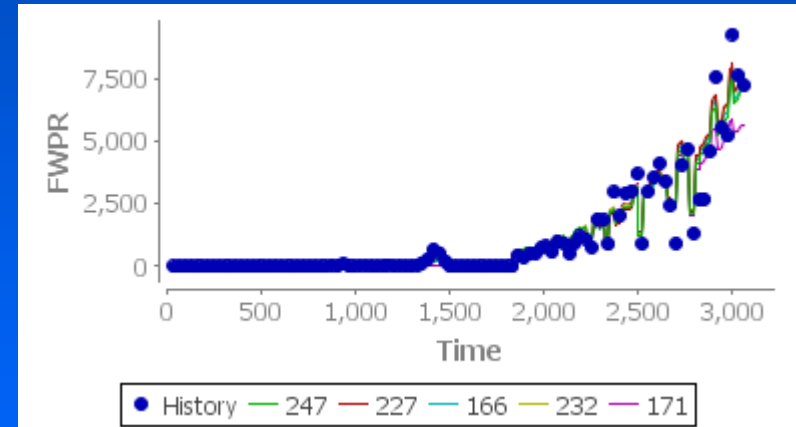
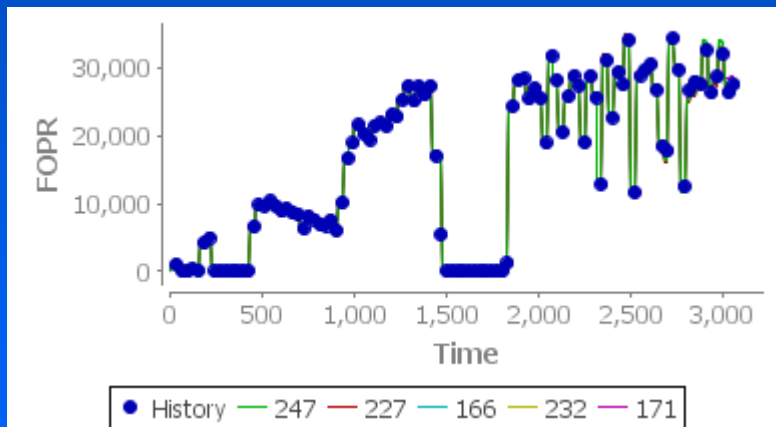
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Field Development Optimisation

- Based on Scapa field
 - Original HM done as part of MSc project
 - HM to field rates (from DECC website)
 - Wells are different from real field
 - 4 injectors, 4 producers

Field Level History Match

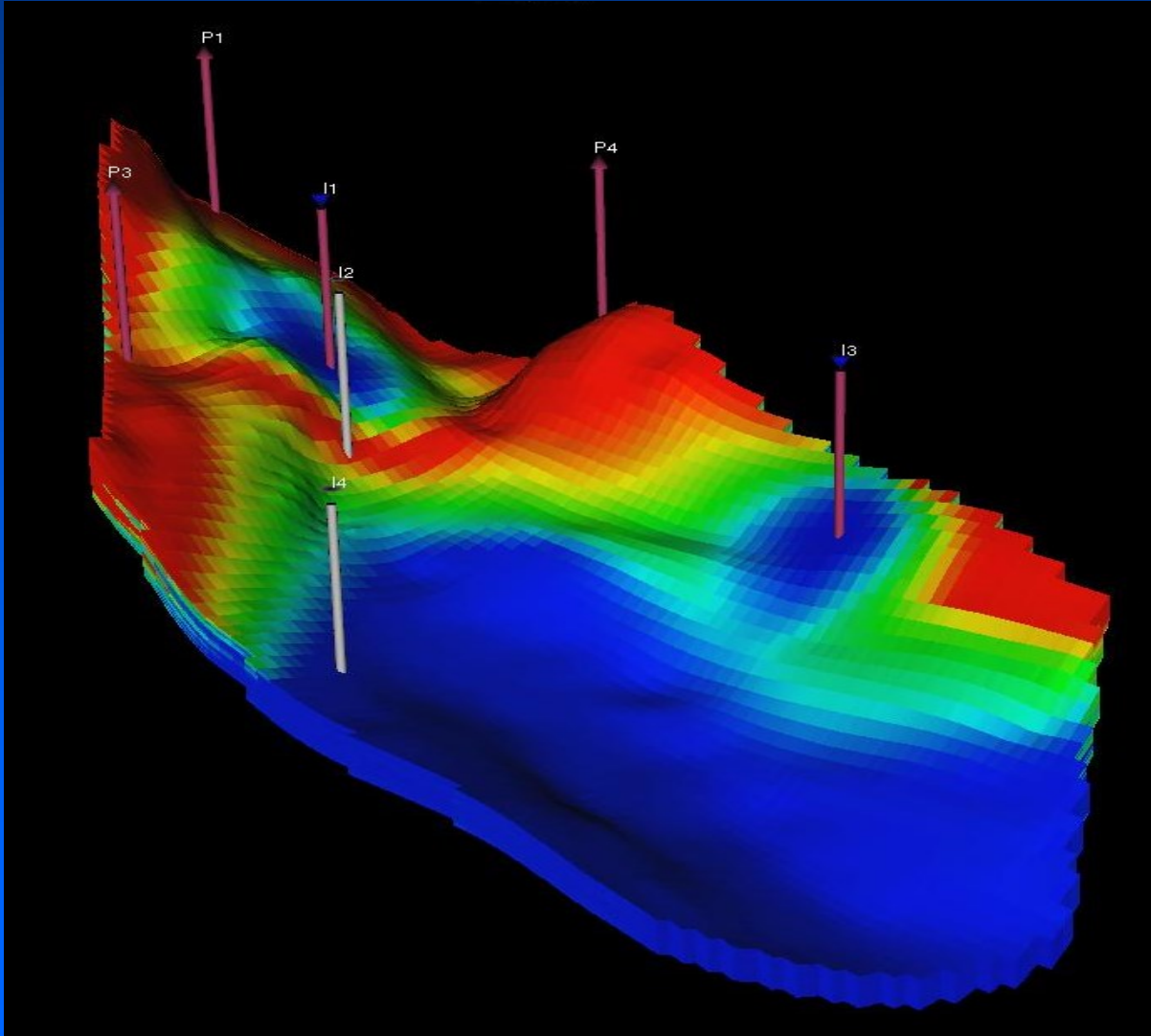
- Match to first 10 years of history
 - Remaining data used to check forecast



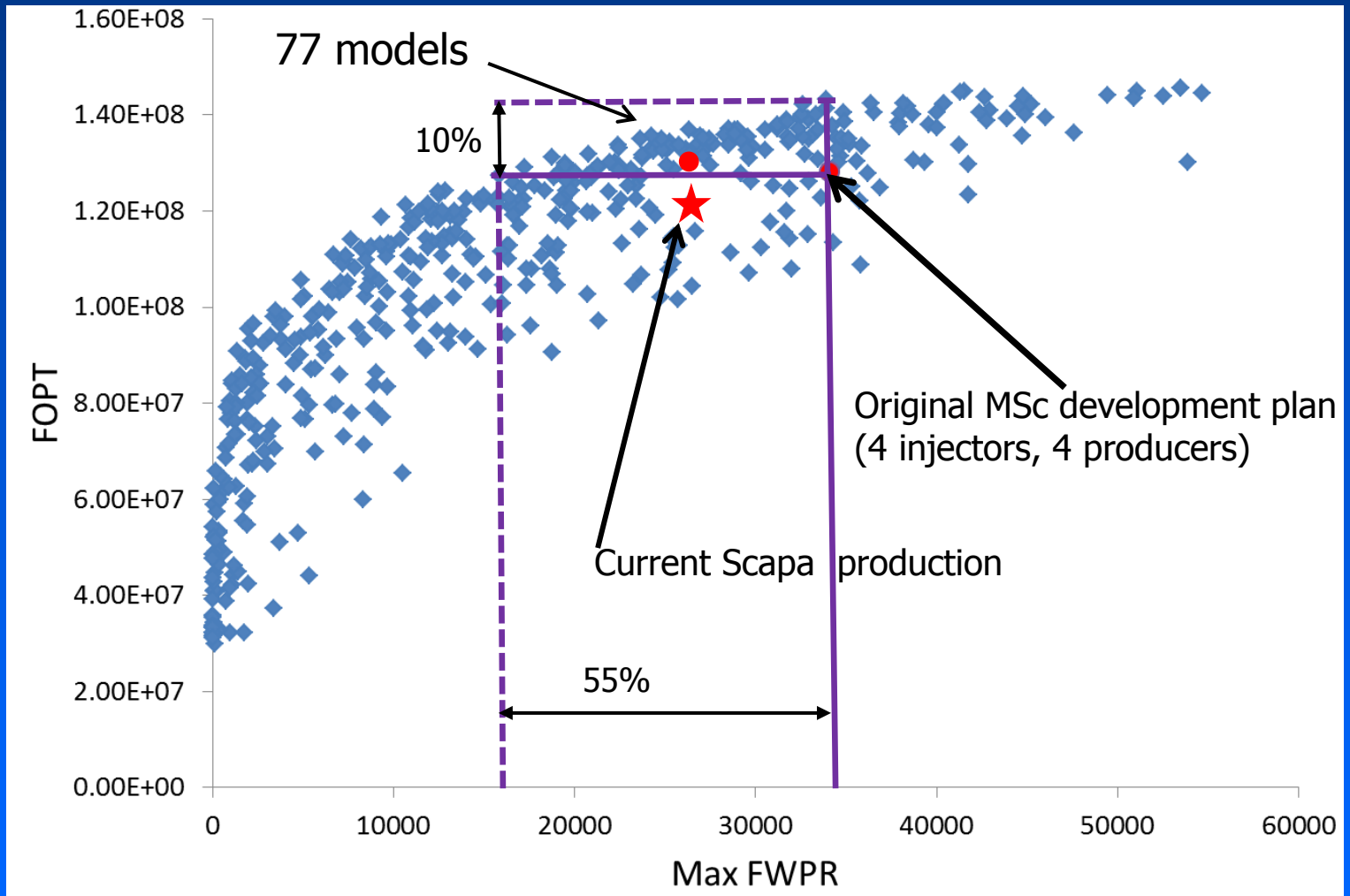
Optimisation

- Multi-Objective
 - Maximise cumulative oil (FOPT)
 - Minimise maximum water rate (FWPR)
- Optimisation variables
 - Well locations (16 variables – i, j for each well)
 - Injection well rates

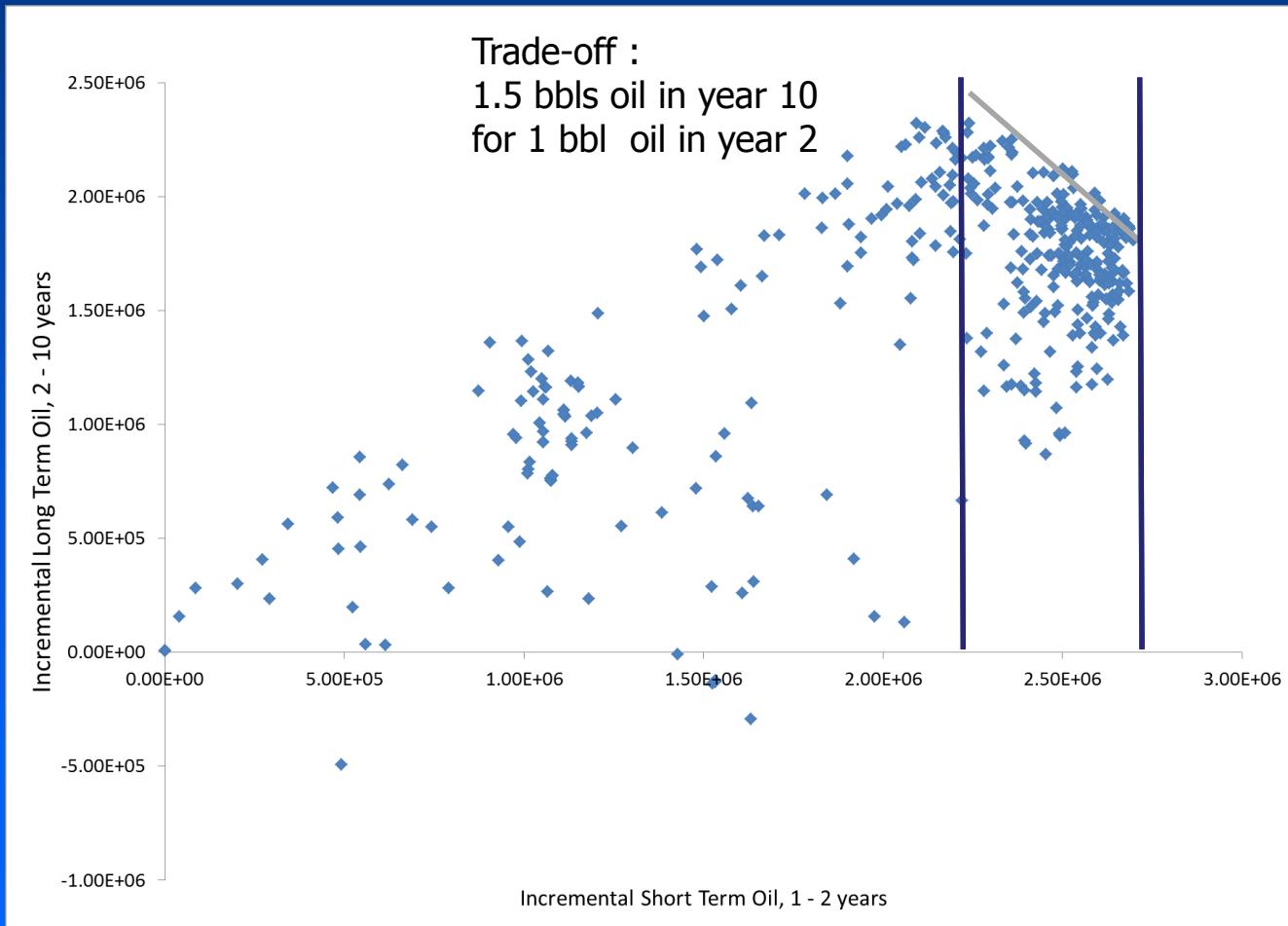
Field Development Optimisation (Scapa)



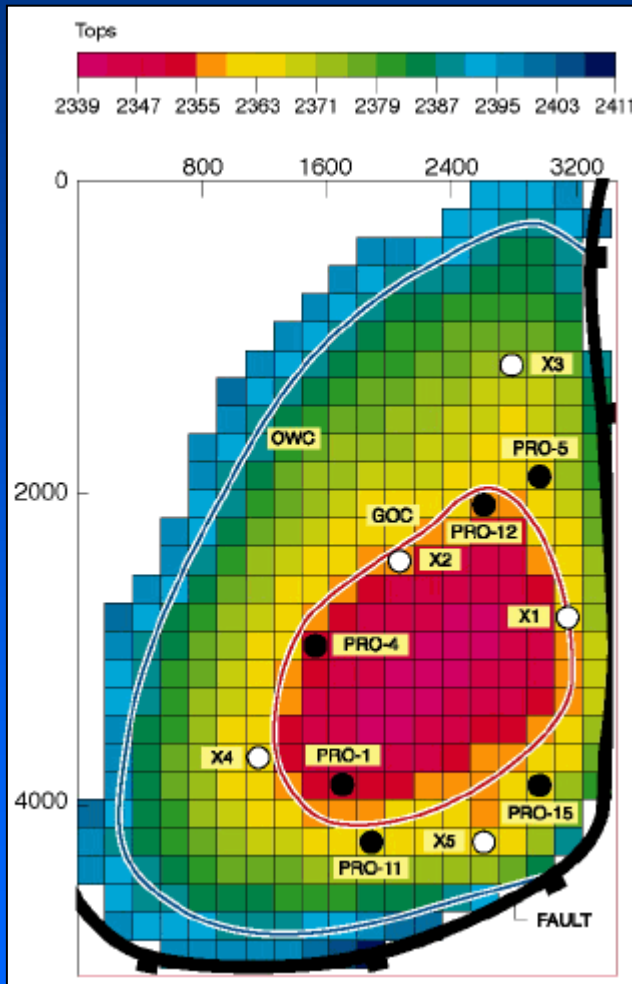
Optimise Field Development Plan



Scapa: Optimise Mid-Life Infill Wells

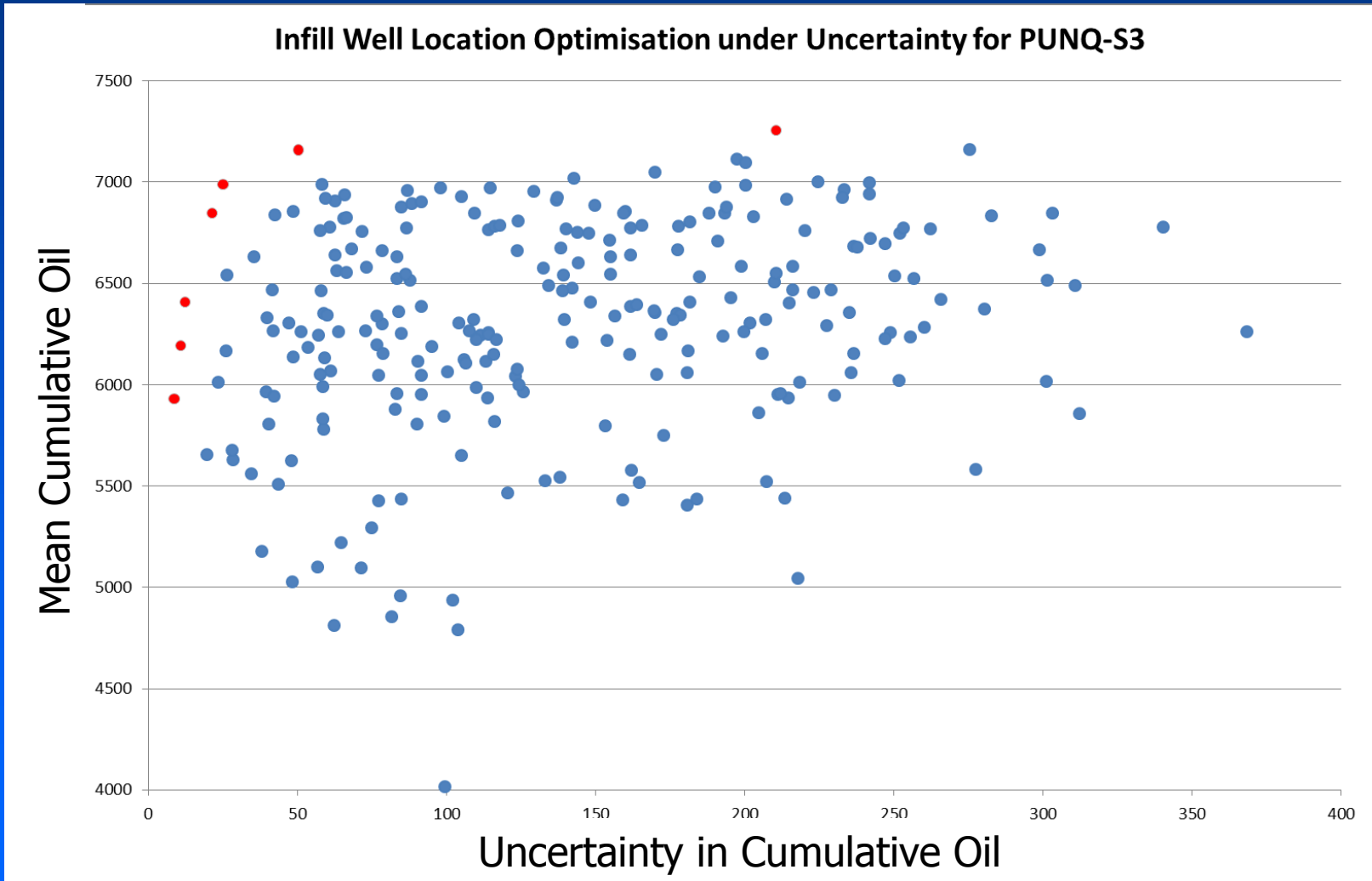


Optimisation Under Uncertainty



- PUNQ-S3
- Multiple HM models
- Optimise infill wells

Optimisation Under Uncertainty



Summary

- History Matching
 - Multi-objective may increase convergence speed, but not always
- Forecasting
 - Multi-objective provides greater coverage of pareto front; can lead to better forecasts
- Optimisation
 - Explore the full range of trade-offs
 - Can include uncertainty

Acknowledgements

- EoN for funding the SO vs MO comparison
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- RFD for licences of tNavigator