

Calibration, validation and data assimilation of PDE models in socio-economic sciences¹

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Pedestrian dynamics

- Understanding the flow of large pedestrian crowds and how individual interactions lead to complex macroscopic patters, such as directional lanes, segregation, ...
- But what are the main driving forces in the individual dynamics and how can we determine them from data ?



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Pedestrian dynamic

Opinion dynamics, price formation and knowledge growth

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Price formation

- Interplay between trading behaviour and rules, transaction costs, fluctuations in the number of buyers and vendors influences the price dynamics.
- What are minimal features necessary in mathematical models to obtain realistic outcomes ? What is the impact of a single factor ?



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Opinion formation, knowledge growth,

- Knowledge and information spreads rapidly in social networks like twitter,
- How can we use this information to understand consumer choice behaviour, economic growth and make predictions about future dynamics ?



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Microscopic models

- The dynamics of each individual and its interactions with all others are described separately.
- Advantage: it's intuitive and rather 'straight forward'.
- $\bullet\,$ Drawback: The more people, the more equations \Rightarrow difficult to predict the large-scale dynamics.

Let $X_i = X_i(t)$ denote a characteristic feature of a single individual at time t, for example his/her position in space, opinion, the price at which he/she is willing to buy/sell a good,

Characteristic changes via 'update rules', for example Newton law of motion

$$dX_i = F(X_1, X_2, \ldots, X_N)dt + \sigma dW_i(t).$$

or by modelling the one-by-one interactions individuals

$$X_i = X_i + \omega a(X_i, X_j) + \eta_i$$

$$X_j = X_j + \omega a(X_j, X_i) + \eta_j.$$

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What are the equations on the macroscopic level ?

PDEs describe the evolution of the overall density with respect to their position and/or velocity in time.

Generic form for the individual density $\varrho = \varrho(x, t)$:

$$\frac{\partial}{\partial t}\varrho(\mathbf{x},t) = \nabla \cdot (m(\varrho)\nabla(\underbrace{U'(\varrho) + W * \varrho + V}_{:=v(\varrho)}),$$

where U corresponds the internal energy, W the interaction energy and V a given external potential.

• Advantage: can be analysed more easily using tools from mathematical analysis.

• Drawback: less intuitive, derivation (from the microscopic level, ad-hoc).

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Individual dynamics

Individual based/off-lattice models such as Newton law of motion (known as the 'Social Force Model'):

 $\begin{aligned} \dot{X}_i(t) &= V_i(t) \\ \dot{V}_i(t) &= F(X_1, \dots, X_N, V_1, \dots, V_N) + G(X_i). \end{aligned}$

Lattice based models (cellular automata, hopping models, ...): State the probability $p_i = p_i(t)$ to find an individual at a discrete lattice site *i* and update it via

$$\frac{dp_i}{dt} = \mathcal{T}_{i-1}^+ p_{i-1} + \mathcal{T}_{i+1}^- p_{i+1} - (\mathcal{T}_i^+ + \mathcal{T}_i^-) p_i.$$

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Nonlinear PDE models for pedestrian dynamics

Instead of describing the individual dynamics we describe the distribution of individuals.

 Boltzmann-type equations for the distribution with respect to position and velocity, that is f = f(x, v, t):

$$\frac{\partial}{\partial t}f(x,v,t) + v \cdot \nabla_x f(x,v,t) + \nabla \cdot (F_f f) = \frac{\sigma^2}{2}\Delta f$$

 Continuity equations for the distribution with respect to their position in space only, for example the Hughes model for pedestrian flow *ρ* = *ρ*(*x*, *t*):

$$\begin{split} \frac{\partial}{\partial t}\varrho(\mathbf{x},t) &= \nabla \cdot (\varrho(1-\varrho)|\nabla \phi|) \\ &|\nabla \phi|^2 = \frac{1}{1-\varrho}. \end{split}$$



Individual trajectories - obtained from cameras²



(a) Kinect sensors mounted on the (b) Density map obtained from sensors. (c) Extracted trajectories. ceiling.

²Seer et al., *Validating social force based models with comprehensive real world motion data*, Transportation Research Procedia, 2014

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Or from sensors placed on the head \dots^3



³Courtesy of Armin Seyfried (Forschungszentrum Jülich), BaSiGo experiments (5 days, 31 experiments, 200 runs, 28 industrial cameras, 2200 participants in total)

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Fundamental diagram⁴



⁴Courtesy of Armin Seyfried (Forschungszentrum Jülich), BaSiGo experiments (5 days, 31 experiments, 200 runs, 28 industrial cameras, 2200 participants in total)

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Calibration and validation in pedestrian dynamics

 Fundamental diagram is commonly used in hyperbolic conservation laws for traffic flow to determine the velocity v = v(g):

$$\frac{\partial}{\partial t}\varrho = \nabla \cdot (\varrho v(\varrho))$$

 \Rightarrow Pedestrians step aside and experimental conditions are not applicable in many conditions.

- Hoogendorn ⁵ determined model parameters in force based models from experimental trajectories using maximum likelihood estimation.
 - \Rightarrow Trajectory data is usually very noisy due to body sway, limited resolution,
- Determine mobilities in the nonlinear macroscopic PDE from macroscopic measurements, such as the flow density.

 \Rightarrow Shall we use 'averaged' data to calibrate PDE models ? What do we learn from that ?

⁵Hoogendorn et al., *Microscopic calibration and validation of pedestrian models - Cross comparison using experimental data*, Pedestrian and Evacuation Dynamics, 2005

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Individual interactions

Boltzmann-type equations: borrow ideas from statistical physics and model interactions between two individuals via 'collisions'.

• Opinion formation:⁶ Toscani suggested the following compromise dynamics if two individuals with opinion X_i and X_j meet:

$$X_i^* = X_i - \omega P(|X_i - X_j|) (X_i - X_j) + \eta_i$$

$$X_j^* = X_j - \omega P(|X_i - X_j|) (X_j - X_i) + \eta_j$$

• Price dynamics:⁷ We consider a buyer willing to buy at price X_i and a vendor willing to sell at price X_j meet. Then the post-interaction prices are determined by the price they agree on $r(X_i, X_j)$ and the transaction costs *a*.

 $X_i^* = r(X_i, X_j) - a$ $X_j^* = r(X_i, X_j) + a$

⁶Toscani, *Kinetic models of opinion formation*, 2006 ⁷Burger, Caffarelli, Markowich and W, *On a Boltzmann type price formation model*, 2013 Is in socia-economic applications Pedestrian dynamics price formation dynamics price for applications of the social second seco

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Individual interactions

Knowledge increase and economic growth⁸:

- Each individual is characterised by its knowledge level X = X(t) and the time S(t) = S(X(t)) he/she is willing to spend on learning.
- If two individuals meet (and exchange knowledge), their 'post-collision' knowledge level corresponds to

$$X_i^* = X_i^* = \max(X_i, X_j)$$

 Each individual decides how much time he/she spend on working or learning by maximising:

$$\max_{S(X(t))} \int_{t'}^{T} e^{-r(t-t')} (1 - S(X(t))) X(t) dt.$$

⁸Lucas & Moll, Knowledge growth and the allocation of time, 2014

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PDE models

Boltzmann-type equation for the distribution of individuals with respect to their position x in space and their velocity v:

$$\frac{\partial}{\partial t}f(x,v,t) - \frac{\sigma^2}{2}\Delta_x f(x,v,t) + v \cdot \nabla_x f(x,v,t) = \mathcal{Q}(f,f)$$

In case of the knowledge growth model this equation is additionally coupled to a Hamilton Jacobi Bellman equation

$$\frac{\partial}{\partial t}V(x,t) - rV(x,t) + \max_{s}[(1-s(x,t))x - \alpha(s(x,t),t)V(x,t)(1-H)*f + \alpha(s(x,t))(1-H)*(V*f)] = 0.$$

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PDE models - asymptotic limits

Price formation model for markets with high trading frequency and low transaction costs \Rightarrow minimal parabolic free boundary problem proposed by Lasry & Lions:

$$\begin{split} & \frac{\partial \varrho_b}{\partial t} - \frac{\partial^2 \varrho_b}{\partial x^2} = \lambda(t)\delta\left(x - p(t) + a\right), & \text{for } x < p(t) \\ & \varrho_b(x,t) > 0 & \text{for } x < p(t) & \text{and } \varrho_b(x,t) = 0 & \text{for } x \ge p(t) \end{split}$$

$$\begin{aligned} &\frac{\partial \varrho_{v}}{\partial t} - \frac{\partial^{2} \varrho_{v}}{\partial x^{2}} = \lambda(t)\delta\left(x - p(t) - a\right), & \text{for } x > p(t)\\ &\varrho_{v}(x,t) > 0 & \text{for } x > p(t) & \text{and } \varrho_{v}(x,t) = 0 & \text{for } x \le p(t), \end{aligned}$$

with a transaction rate

$$\lambda(t) = -\frac{\partial \varrho_{b}}{\partial x} \left(p(t), t \right) = \frac{\partial \varrho_{v}}{\partial x} \left(p(t), t \right).$$



GDP, price dynamics, hashtags,

- Price formation: Given the price p = p(t) and the transaction rate $\lambda = \lambda(t)$ for a certain time interval $t \in [0, T]$, can we reconstruct the buyer-vendor distribution and predict the price evolution for t > T?⁹
- $\bullet\,$ Knowledge growth: Balanced growth path solutions $\Rightarrow\,$ exponential growth of the overall production

Knowing that the GDP of most countries grow in the long-term run \Rightarrow what are the implications on the individual interactions or knowledge growth in general ?

- Opinion formation: With more and more data available, such as the dissemination of information or the individual exchange rates on certain topics (for example via Twitter)
 - \Rightarrow How can we include this information in models and use it to calibrate them ?

⁹J.P. Puel, A nonstandard approach to a data assimilation problem and Tichonov regularisation revisited, SICON, 2009

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Data assimilation in socio-economic applications

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Data assimilation in socio-economic applications matching bad models with even worse data ?!?!

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Data assimilation in socio-economic applications matching bad models with even worse data ?!?!

But to be fair: there is a huge potential, but one has to keep the validity and restrictions in mind.

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